

## ON SOME PROPERTIES OF CONTINUOUS $G$ -FRAMES AND RIESZ-TYPE CONTINUOUS $G$ -FRAMES

Mohammad Reza Abdollahpour and Yavar khedmati

*Department of Mathematics, Faculty of Sciences,  
University of Mohaghegh Ardabili, Ardabil 56199-11367, Iran  
e-mails: m.abdollah@uma.ac.ir; mrabdollahpour@yahoo.com;  
khedmati.y@uma.ac.ir, khedmatiy@gmail.com*

(Received 6 October 2015; accepted 31 March 2016)

In this paper we provide some necessary and sufficient conditions under which, a family of bounded operators is a continuous  $g$ -frame (Riesz-type continuous  $g$ -frame). Also, we study stability of duals of continuous  $g$ -frames.

**Key words** : Continuous frame; continuous  $g$ -frame; Riesz-type continuous  $g$ -frame.

### 1. INTRODUCTION

In 1952, the concept of frames for Hilbert spaces was defined by Duffin and Schaeffer [4]. Frames are important tools in the signal processing, image processing, data compression, etc. In 1993, Ali *et al.*, [2] developed the notion of ordinary frame to a family indexed by a measurable space which are known as continuous frames.

*Definition 1.1* — Let  $\mathcal{H}$  be a complex Hilbert space and  $(\Omega, \mu)$  be a measure space. A mapping  $F : \Omega \rightarrow \mathcal{H}$  is called a continuous frame with respect to  $(\Omega, \mu)$ , if

- (i)  $F$  is weakly-measurable, i.e., for all  $f \in \mathcal{H}$ ,  $\omega \rightarrow \langle f, F(\omega) \rangle$  is a measurable function on  $\Omega$ ,
- (ii) there exist constants  $A_F, B_F > 0$  such that

$$A_F \|f\|^2 \leq \int_{\Omega} |\langle f, F(\omega) \rangle|^2 d\mu(\omega) \leq B_F \|f\|^2, \quad f \in \mathcal{H}.$$

In 2006,  $g$ -frames or generalized frames introduced by Sun [6] and Abdollahpour and Faroughi [1] introduced and investigated continuous  $g$ -frames and Riesz-type continuous  $g$ -frames. In the rest

of this paper we assume that  $\mathcal{H}$  is a complex Hilbert space and  $(\Omega, \mu)$  is a measure space with positive measure  $\mu$  and  $\{\mathcal{K}_\omega : \omega \in \Omega\}$  is a family of Hilbert spaces. Now, we summarize some facts about continuous  $g$ -frames from [1].

We say that  $F \in \prod_{\omega \in \Omega} \mathcal{K}_\omega$  is strongly measurable if  $F$  as a mapping of  $\Omega$  to  $\bigoplus_{\omega \in \Omega} \mathcal{K}_\omega$  is measurable, where

$$\prod_{\omega \in \Omega} \mathcal{K}_\omega = \left\{ f : \Omega \rightarrow \bigcup_{\omega \in \Omega} \mathcal{K}_\omega : f(\omega) \in \mathcal{K}_\omega \right\}.$$

*Definition 1.2* — We say that  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a continuous  $g$ -frame for  $\mathcal{H}$  with respect to  $\{\mathcal{K}_\omega : \omega \in \Omega\}$  if

- (i) for each  $f \in \mathcal{H}$ ,  $\{\Lambda_\omega f : \omega \in \Omega\}$  is strongly measurable,
- (ii) there are two constants  $0 < A_\Lambda \leq B_\Lambda < \infty$  such that

$$A_\Lambda \|f\|^2 \leq \int_{\Omega} \|\Lambda_\omega(f)\|^2 d\mu(\omega) \leq B_\Lambda \|f\|^2, \quad f \in \mathcal{H}. \quad (1.1)$$

We call  $A_\Lambda, B_\Lambda$  the lower and upper continuous  $g$ -frame bounds, respectively.  $\Lambda$  is called a tight continuous  $g$ -frame if  $A_\Lambda = B_\Lambda$ , and a Parseval continuous  $g$ -frame if  $A_\Lambda = B_\Lambda = 1$ . If for each  $\omega \in \Omega$ ,  $\mathcal{K} = \mathcal{K}_\omega$ , then  $\Lambda$  is called a continuous  $g$ -frame for  $\mathcal{H}$  with respect to  $\mathcal{K}$ . A family  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is called a continuous  $g$ -Bessel family for  $\mathcal{H}$  with respect to  $\{\mathcal{K}_\omega : \omega \in \Omega\}$  if the right hand inequality in (1.1) holds for all  $f \in \mathcal{H}$ . In this case,  $B_\Lambda$  is called the Bessel constant.

If there is no confusion, we use continuous  $g$ -frame (continuous  $g$ -Bessel family) instead of continuous  $g$ -frame for  $\mathcal{H}$  with respect to  $\{\mathcal{K}_\omega : \omega \in \Omega\}$  (continuous  $g$ -Bessel family for  $\mathcal{H}$  with respect to  $\{\mathcal{K}_\omega : \omega \in \Omega\}$ ).

*Proposition 1.3* [1] — Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be a continuous  $g$ -frame. There exists a unique positive and invertible operator  $S_\Lambda : \mathcal{H} \rightarrow \mathcal{H}$  such that for each  $f, g \in \mathcal{H}$

$$\langle S_\Lambda f, g \rangle = \int_{\Omega} \langle f, \Lambda_\omega^* \Lambda_\omega g \rangle d\mu(\omega), \quad f, g \in \mathcal{H},$$

and  $A_\Lambda I \leq S_\Lambda \leq B_\Lambda I$ .

The operator  $S_\Lambda$  in Proposition 1.3 is called the continuous  $g$ -frame operator of  $\Lambda$ . Also, we have

$$\begin{aligned} \langle f, g \rangle &= \int_{\Omega} \langle S_\Lambda^{-1} f, \Lambda_\omega^* \Lambda_\omega g \rangle d\mu(\omega) \\ &= \int_{\Omega} \langle f, \Lambda_\omega^* \Lambda_\omega S_\Lambda^{-1} g \rangle d\mu(\omega), \quad f, g \in \mathcal{H}. \end{aligned} \quad (1.2)$$

We consider the space

$$\widehat{\mathcal{K}} = \left\{ F \in \prod_{\omega \in \Omega} \mathcal{K}_\omega : F \text{ is strongly measurable, } \int_{\Omega} \|F(\omega)\|^2 d\mu(\omega) < \infty \right\}.$$

It is clear that  $\widehat{\mathcal{K}}$  is a Hilbert space with point wise operations and the inner product given by

$$\langle F, G \rangle = \int_{\Omega} \langle F(\omega), G(\omega) \rangle d\mu(\omega).$$

*Proposition 1.4* [1] — Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be a continuous  $g$ -Bessel family. Then the mapping  $T_\Lambda : \widehat{\mathcal{K}} \rightarrow \mathcal{H}$  defined by

$$\langle T_\Lambda F, g \rangle = \int_{\Omega} \langle \Lambda_\omega^* F(\omega), g \rangle d\mu(\omega), \quad F \in \widehat{\mathcal{K}}, \quad g \in \mathcal{H}, \quad (1.3)$$

is linear and bounded with  $\|T_\Lambda\| \leq \sqrt{B_\Lambda}$ . Also, for each  $g \in \mathcal{H}$  we have

$$T_\Lambda^*(g)(\omega) = \Lambda_\omega g, \quad \omega \in \Omega.$$

**Theorem 1.5** [1] — Let  $(\Omega, \mu)$  be a measure space, where  $\mu$  is  $\sigma$ -finite. Suppose that  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a family of operators such that  $\{\Lambda_\omega f : \omega \in \Omega\}$  is strongly measurable, for each  $f \in \mathcal{H}$ . Then  $\Lambda$  is a continuous  $g$ -frame if and only if the operator  $T_\Lambda : \widehat{\mathcal{K}} \rightarrow \mathcal{H}$  defined by (1.3) is a bounded and onto operator.

The operators  $T_\Lambda$  and  $T_\Lambda^*$  in Theorem 1.8 are called synthesis and analysis operators of  $\Lambda$ , respectively.

*Definition 1.6* — Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  and  $\Theta = \{\Theta_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be two continuous  $g$ -frames such that

$$\langle f, g \rangle = \int_{\Omega} \langle f, \Theta_\omega^* \Lambda_\omega g \rangle d\mu(\omega), \quad f, g \in \mathcal{H},$$

then  $\Theta$  is called a dual continuous  $g$ -frame of  $\Lambda$ .

Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be a continuous  $g$ -frame. Then  $\widetilde{\Lambda} = \{\Lambda_\omega S_\Lambda^{-1} \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a continuous  $g$ -frame and by (1.2),  $\widetilde{\Lambda}$  is a dual of  $\Lambda$ . we call  $\widetilde{\Lambda}$  the canonical dual of  $\Lambda$ . One can always get a tight continuous  $g$ -frame from any continuous  $g$ -frame, in fact, if  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a continuous  $g$ -frame for  $\mathcal{H}$  then  $\{\Lambda_\omega S_\Lambda^{-1/2} \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a Parseval continuous  $g$ -frame.

*Definition 1.7* — Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  and  $\Theta = \{\Theta_\omega \in B(\mathcal{K}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be two continuous  $g$ -frames. Then  $\Lambda$  and  $\Theta$  are said similar if there is an invertible operator  $S : \mathcal{H} \rightarrow \mathcal{K}$  such that  $\Theta_\omega S = \Lambda_\omega$  for a.e.  $\omega \in \Omega$ .

Two continuous  $g$ -Bessel families  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  and  $\Theta = \{\Theta_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  are weakly equal, if for all  $f \in \mathcal{H}$ ,

$$\Lambda_\omega f = \Theta_\omega f, \text{ a.e. } \omega \in \Omega.$$

*Proposition 1.8* [1] — Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  and  $\Theta = \{\Theta_\omega \in B(\mathcal{K}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be two continuous  $g$ -frames. Then  $\Lambda$  and  $\Theta$  are similar if and only if their analysis operators have the same ranges (weakly).

If the continuous  $g$ -frame  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  have only one dual(weakly), i.e., every dual of  $\Lambda$  is weakly equal to the canonical dual of  $\Lambda$ , then  $\Lambda$  is called a Riesz-type continuous  $g$ -frame.

**Theorem 1.9** — Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be a continuous  $g$ -frame. Then  $\Lambda$  is a Riesz-type continuous  $g$ -frame if and only if  $\text{Range}T_\Lambda^* = \widehat{\mathcal{K}}$ .

## 2. SOME NEW RESULTS FOR CONTINUOUS G-FRAMES

In this section by generalizing some results of [5], we give some necessary and sufficient conditions that a family of bounded operators  $\{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a continuous  $g$ -frame (Riesz-type continuous  $g$ -frame). In this section until the end of Proposition 2.5,  $\mathcal{K}_\omega$  is a finite dimensional Hilbert space with orthonormal basis  $\{e_{\omega,j} : j \in J_\omega\}$  for all  $\omega \in \Omega$ .

*Proposition 2.1* — Let  $\{e_i\}_{i \in I}$  be an orthonormal basis for  $\mathcal{H}$  and  $\{e_{\omega j}\}_{j \in J_\omega}$  be an orthonormal basis for  $\mathcal{K}_\omega$ , for all  $\omega \in \Omega$ . Then the following are equivalent:

- (i)  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a Parseval continuous  $g$ -frame.
- (ii) There exist an orthonormal set  $\{\psi_i\}_{i \in I} \subseteq \widehat{\mathcal{K}}$  such that  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$  for a.e.  $\omega \in \Omega$  and for all  $f \in \mathcal{H}$ ,

$$\Lambda_\omega f = \sum_{i \in I} \langle f, e_i \rangle \psi_i(\omega), \quad \text{a.e. } \omega \in \Omega.$$

PROOF : (i)  $\Rightarrow$  (ii) We consider  $\psi_i = T_\Lambda^* e_i$ , for all  $i \in I$ . Then

$$\|\psi_i\|^2 = \|T_\Lambda^* e_i\|^2 = \int_\Omega \|\Lambda_\omega e_i\|^2 d\mu(\omega) = \|e_i\|^2 = 1,$$

and

$$\langle \psi_i, \psi_j \rangle = \langle T_\Lambda^* e_i, T_\Lambda^* e_j \rangle = \int_\Omega \langle \Lambda_\omega e_i, \Lambda_\omega e_j \rangle d\mu(\omega) = \langle e_i, e_j \rangle = 0, \quad i \neq j.$$

On the other hand,

$$\begin{aligned} \sum_{i \in I} \|\psi_i(\omega)\|^2 &= \sum_{i \in I} \|\Lambda_\omega e_i\|^2 = \sum_{i \in I} \left\| \sum_{j \in J_\omega} \langle \Lambda_\omega e_i, e_{\omega j} \rangle e_{\omega j} \right\|^2 \\ &= \sum_{j \in J_\omega} \sum_{i \in I} |\langle e_i, \Lambda_\omega^* e_{\omega j} \rangle|^2 = \sum_{j \in J_\omega} \|\Lambda_\omega^* e_{\omega j}\|^2 < \infty. \end{aligned}$$

Furthermore, for any  $f \in \mathcal{H}$ ,

$$\Lambda_\omega f = \sum_{i \in I} \langle f, e_i \rangle \Lambda_\omega e_i = \sum_{i \in I} \langle f, e_i \rangle \psi_i(\omega).$$

Conversely, since  $\{\psi_i\}_{i \in I} \subseteq \widehat{\mathcal{K}}$  is an orthonormal set then for any  $f \in \mathcal{H}$

$$\begin{aligned} \int_\Omega \|\Lambda_\omega f\|^2 d\mu(\omega) &= \int_\Omega \left\| \sum_{i \in I} \langle f, e_i \rangle \psi_i(\omega) \right\|^2 d\mu(\omega) \\ &= \left\| \sum_{i \in I} \langle f, e_i \rangle \psi_i \right\|^2 \\ &= \sum_{i \in I} |\langle f, e_i \rangle|^2 = \|f\|^2. \end{aligned}$$

We recall that a Riesz basis for a Hilbert space  $\mathcal{H}$  is a family of the form  $\{U e_i\}_{i \in I}$ , where  $\{e_i\}_{i \in I}$  is an orthonormal basis for  $\mathcal{H}$  and  $U : \mathcal{H} \rightarrow \mathcal{H}$  is a bounded bijective operator.  $\square$

**Theorem 2.2** — *Let  $\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega)$  be given for all  $\omega \in \Omega$ . The following are equivalent:*

- (i)  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a continuous g-frame.
- (ii)  $\Lambda_\omega f = \sum_{i \in I} \langle f, e_i \rangle \psi_i(\omega)$  for some orthonormal basis  $\{e_i\}_{i \in I}$  of  $\mathcal{H}$  and some family  $\{\psi_i\}_{i \in I} \subseteq \widehat{\mathcal{K}}$  with the property that  $\{\psi_i\}_{i \in I}$  is a Riesz basis for  $\overline{\text{span}}\{\psi_i\}_{i \in I}$  and  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$  for a.e.  $\omega \in \Omega$ .
- (iii)  $\Lambda_\omega f = \sum_{i \in I} \langle f, h_i \rangle \psi_i(\omega)$  for some Riesz basis  $\{h_i\}_{i \in I}$  of  $\mathcal{H}$  and some orthonormal set  $\{\psi_i\}_{i \in I} \subseteq \widehat{\mathcal{K}}$  and with the property that  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$  for a.e.  $\omega \in \Omega$ .
- (iv)  $\Lambda_\omega f = \sum_{i \in I} \langle f, h_i \rangle \psi_i(\omega)$  for some Riesz basis  $\{h_i\}_{i \in I}$  of  $\mathcal{H}$  and some family  $\{\psi_i\}_{i \in I} \subseteq \widehat{\mathcal{K}}$  with the property that  $\{\psi_i\}_{i \in I}$  is a Riesz basis for  $\overline{\text{span}}\{\psi_i\}_{i \in I}$  and  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$  for a.e.  $\omega \in \Omega$ .

PROOF : (i)  $\Rightarrow$  (ii) Let  $\{e_i\}_{i \in I}$  be an orthonormal basis of  $\mathcal{H}$  and  $\psi_i = T_\Lambda^* e_i$  for all  $i \in I$ . Then for any finite sequence of scalars  $\{c_k\}$ , we have

$$\begin{aligned} \left\| \sum c_k \psi_k \right\|^2 &= \left\| \sum c_k T_\Lambda^* e_k \right\|^2 = \left\| T_\Lambda^* \left( \sum c_k e_k \right) \right\|^2 \\ &= \int_\Omega \left\| \Lambda_\omega \left( \sum c_k e_k \right) \right\|^2 d\mu(\omega), \end{aligned}$$

So

$$\begin{aligned} A_\Lambda \sum |c_k|^2 &= A_\Lambda \left\| \sum c_k e_k \right\|^2 \leq \left\| \sum c_k \psi_k \right\|^2 \\ &\leq B_\Lambda \left\| \sum c_k e_k \right\|^2 = B_\Lambda \sum |c_k|^2. \end{aligned}$$

Therefore, by [3, Theorem 3.6.6],  $\{\psi_i\}_{i \in I}$  is a Riesz basis for  $\overline{\text{span}}\{\psi_i\}_{i \in I}$ . We also have  $\Lambda_\omega f = \sum_{i \in I} \langle f, e_i \rangle \psi_i(\omega)$  and  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$ .

(ii)  $\Rightarrow$  (i) Since  $\{\psi_i\}_{i \in I} \subseteq \widehat{\mathcal{K}}$  is a Riesz basis for  $\overline{\text{span}}\{\psi_i\}_{i \in I}$ , there exist  $B \geq A > 0$  such that

$$\begin{aligned} A \|f\|^2 &= A \sum_{i \in I} |\langle f, e_i \rangle|^2 \leq \left\| \sum_{i \in I} \langle f, e_i \rangle \psi_i \right\|^2 \\ &\leq B \sum_{i \in I} |\langle f, e_i \rangle|^2 = B \|f\|^2. \end{aligned}$$

Thus

$$A \|f\|^2 \leq \int_\Omega \|\Lambda_\omega f\|^2 d\mu(\omega) = \left\| \sum_{i \in I} \langle f, e_i \rangle \psi_i \right\|^2 \leq B \|f\|^2.$$

(i)  $\Rightarrow$  (iii) Let  $\{e_i\}_{i \in I}$  be an orthonormal basis of  $\mathcal{H}$ . By Proposition 2.1, there exists an orthonormal set  $\{\psi_i\}_{i \in I}$  in  $\widehat{\mathcal{K}}$  such that  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$  for a.e.  $\omega \in \Omega$ , and for all  $g \in \mathcal{H}$

$$\Lambda_\omega S_\Lambda^{-1/2} g = \sum_{i \in I} \langle g, e_i \rangle \psi_i(\omega), \quad \text{a.e. } \omega \in \Omega.$$

For any  $f \in \mathcal{H}$  there exist  $g \in \mathcal{H}$  such that  $S_\Lambda^{-1/2} g = f$ . Thus

$$\Lambda_\omega f = \Lambda_\omega S_\Lambda^{-1/2} g = \sum_{i \in I} \langle S_\Lambda^{1/2} f, e_i \rangle \psi_i(\omega) = \sum_{i \in I} \langle f, S_\Lambda^{1/2} e_i \rangle \psi_i(\omega).$$

It is sufficient to take  $h_i = S_\Lambda^{1/2} e_i$ , for all  $i \in I$ .

(iii)  $\Rightarrow$  (i) Let  $\{e_i\}_{i \in I}$  be an orthonormal basis for  $\mathcal{H}$  and  $U \in B(\mathcal{H})$  be a bijective operator and

$h_i = Ue_i$  for all  $i \in I$ . Then for any  $f \in \mathcal{H}$  we have

$$\begin{aligned} \int_{\Omega} \|\Lambda_{\omega} f\|^2 d\mu(\omega) &= \int_{\Omega} \left\| \sum_{i \in I} \langle f, h_i \rangle \psi_i(\omega) \right\|^2 d\mu(\omega) \\ &= \left\| \sum_{i \in I} \langle f, h_i \rangle \psi_i \right\|^2 \\ &= \sum_{i \in I} |\langle f, h_i \rangle|^2 = \sum_{i \in I} |\langle U^* f, e_i \rangle|^2. \end{aligned}$$

So

$$\|U^{-1}\|^{-2} \|f\|^2 \leq \int_{\Omega} \|\Lambda_{\omega} f\|^2 d\mu(\omega) = \sum_{i \in I} |\langle f, h_i \rangle|^2 \leq \|U\|^2 \|f\|^2, \quad f \in \mathcal{H}.$$

(iv)  $\Rightarrow$  (i) There exist  $C, D > 0$  such that

$$C\|f\|^2 \leq \sum_{i \in I} |\langle f, h_i \rangle|^2 \leq D\|f\|^2, \quad f \in \mathcal{H}.$$

On the other hand, let  $B \geq A > 0$  be the bounds of Riesz basis  $\{\psi_i\}_{i \in I}$ . Then

$$\begin{aligned} AC\|f\|^2 &\leq A \sum_{i \in I} |\langle f, h_i \rangle|^2 \leq \left\| \sum_{i \in I} \langle f, h_i \rangle \psi_i \right\|^2 \\ &= \int_{\Omega} \left\| \sum_{i \in I} \langle f, h_i \rangle \psi_i(\omega) \right\|^2 d\mu(\omega) \\ &\leq B \sum_{i \in I} |\langle f, h_i \rangle|^2 \leq BD\|f\|^2. \end{aligned}$$

for all  $f \in \mathcal{H}$ . According to the (i)  $\Rightarrow$  (ii) the implication (i)  $\Rightarrow$  (iv) is obvious.  $\square$

*Proposition 2.3* — The following are equivalent:

(i) There exists a Riesz-type continuous  $g$ -frame  $\Lambda = \{\Lambda_{\omega} \in B(\mathcal{H}, \mathcal{K}_{\omega}) : \omega \in \Omega\}$  for  $\mathcal{H}$ .

(ii) There exist an orthonormal basis  $\{\psi_i\}_{i \in I}$  for  $\widehat{\mathcal{K}}$  such that

$$\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty, \quad a.e. \ \omega \in \Omega.$$

(iii) For every orthonormal basis  $\{\phi_i\}_{i \in I}$  for  $\widehat{\mathcal{K}}$  we have

$$\sum_{i \in I} \|\phi_i(\omega)\|^2 < \infty, \quad a.e. \ \omega \in \Omega.$$

PROOF : (i)  $\Rightarrow$  (ii) By Theorem 2.2,  $\Lambda_\omega f = \sum_{i \in I} \langle f, h_i \rangle \psi_i(\omega)$  for some Riesz basis  $\{h_i\}_{i \in I}$  of  $\mathcal{H}$  and some orthonormal set  $\{\psi_i\}_{i \in I} \subseteq \widehat{\mathcal{K}}$  with the property that  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$  for a.e.  $\omega \in \Omega$ . By Theorem 1.9, for any  $\psi$  in  $\widehat{\mathcal{K}}$  there exists  $f \in \mathcal{H}$  such that  $T_\Lambda^* f = \psi$ . Thus

$$\psi = \sum_{i \in I} \langle f, h_i \rangle \psi_i.$$

So,  $\overline{\text{span}}\{\psi_i\}_{i \in I} = \widehat{\mathcal{K}}$ , therefore  $\{\psi_i\}_{i \in I}$  is an orthonormal basis for  $\widehat{\mathcal{K}}$ .

(ii)  $\Rightarrow$  (i) Let us define  $\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega)$  by  $\Lambda_\omega f = \sum_{i \in I} \langle f, e_i \rangle \psi_i(\omega)$  for all  $\omega \in \Omega$ , where  $\{e_i\}_{i \in I}$  is an orthonormal basis for  $\mathcal{H}$ . By Proposition 2.1,  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a Parseval continuous  $g$ -frame. For any  $\psi$  in  $\widehat{\mathcal{K}}$  we have  $\psi = \sum_{i \in I} \langle \psi, \psi_i \rangle \psi_i$ . So we have

$$\begin{aligned} T_\Lambda^* \left( \sum_{j \in I} \langle \psi, \psi_j \rangle e_j \right) (\omega) &= \Lambda_\omega \left( \sum_{j \in I} \langle \psi, \psi_j \rangle e_j \right) \\ &= \sum_{i \in I} \left\langle \sum_{j \in I} \langle \psi, \psi_j \rangle e_j, e_i \right\rangle \psi_i(\omega) \\ &= \sum_{i \in I} \langle \psi, \psi_i \rangle \psi_i(\omega) = \psi(\omega), \end{aligned}$$

for all  $\omega \in \Omega$ . This means that  $T_\Lambda$  is surjective and by Theorem 1.9, the proof is complete.

(iii)  $\Rightarrow$  (ii) It is clear.

(i)  $\Rightarrow$  (iii) By assumption,  $\Gamma = \{\Lambda_\omega S_\Lambda^{-1/2} : \omega \in \Omega\}$  is a Parseval continuous  $g$ -frame and  $\text{Range} T_\Gamma^* = \text{Range} T_\Lambda^* = \widehat{\mathcal{K}}$ . Therefore,  $T_\Gamma^*$  is a surjective isometry and so  $T_\Gamma$  is unitary. Let  $\{\phi_i\}_{i \in I}$  be an orthonormal basis for  $\widehat{\mathcal{K}}$ . Let us consider  $e_i = T_\Gamma \phi_i$ , for all  $i \in I$ . Then,  $\{e_i\}_{i \in I}$  is an orthonormal basis for  $\mathcal{H}$  and

$$\begin{aligned} \sum_{i \in I} \|\phi_i(\omega)\|^2 &= \sum_{i \in I} \left\| \sum_{j \in J_\omega} \langle \phi_i(\omega), e_{\omega j} \rangle e_{\omega j} \right\|^2 \\ &= \sum_{i \in I} \sum_{j \in J_\omega} |\langle \phi_i(\omega), e_{\omega j} \rangle|^2 \\ &= \sum_{i \in I} \sum_{j \in J_\omega} |\langle \Lambda_\omega S_\Lambda^{-1/2} e_i, e_{\omega j} \rangle|^2 \\ &= \sum_{j \in J_\omega} \sum_{i \in I} |\langle e_i, S_\Lambda^{-1/2} \Lambda_\omega^* e_{\omega j} \rangle|^2 \\ &= \sum_{j \in J_\omega} \|S_\Lambda^{-1/2} \Lambda_\omega^* e_{\omega j}\|^2 < \infty, \end{aligned}$$

for a.e.  $\omega \in \Omega$ .



*Corollary 2.4* — Let  $M$  be a closed subspace of  $\widehat{\mathcal{K}}$ . Then the following are equivalent:

- (i) There exists a continuous  $g$ -frame  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  for  $\mathcal{H}$  and  $\text{Range} T_\Lambda^* = M$ .
- (ii) There exist an orthonormal basis  $\{\psi_i\}_{i \in I}$  for  $M$  with the property that  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$ , for a.e.  $\omega \in \Omega$ .
- (iii) Every orthonormal basis  $\{\phi_i\}_{i \in I}$  for  $M$  satisfies  $\sum_{i \in I} \|\phi_i(\omega)\|^2 < \infty$ , for a.e.  $\omega \in \Omega$ .

PROOF : (i)  $\Rightarrow$  (ii) Since  $\Lambda$  is a continuous  $g$ -frame,  $\Gamma = \{\Lambda_\omega S_\Lambda^{-1/2} \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a Parseval continuous  $g$ -frame. Let  $\{e_i\}_{i \in I}$  be an orthonormal basis for  $\mathcal{H}$ . If we take  $\psi_i = T_\Gamma^* e_i$ , for all  $i \in I$  then by Proposition 2.1,  $\{\psi_i\}_{i \in I}$  is an orthonormal set of  $M$  with the property that  $\sum_{i \in I} \|\psi_i(\omega)\|^2 < \infty$  for a.e.  $\omega \in \Omega$  and

$$\Lambda_\omega S_\Lambda^{-1/2} g = \sum_{i \in I} \langle g, e_i \rangle \psi_i(\omega), \quad \text{a.e. } \omega \in \Omega, \quad g \in \mathcal{H}.$$

For any  $\psi \in M$  there exists  $f \in \mathcal{H}$  such that  $T_\Lambda^* f = \psi$ . Let  $g = S_\Lambda^{1/2} f$ , then

$$\psi(\omega) = \Lambda_\omega f = \Lambda_\omega S_\Lambda^{-1/2} g = \sum_{i \in I} \langle g, e_i \rangle \psi_i(\omega).$$

(ii)  $\Rightarrow$  (i) Let  $\{e_i\}_{i \in I}$  be an orthonormal basis for  $\mathcal{H}$ . We define bounded operator

$$\Lambda_\omega : \mathcal{H} \rightarrow \mathcal{K}_\omega, \quad \Lambda_\omega f = \sum_{i \in I} \langle f, e_i \rangle \psi_i(\omega),$$

for a.e.  $\omega \in \Omega$ . Then by Proposition 2.1,  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a parseval continuous  $g$ -frame. If  $\psi \in M$ , then  $\psi = \sum_{i \in I} \langle \psi, \psi_i \rangle \psi_i$  and

$$T_\Lambda^* \left( \sum_{i \in I} \langle \psi, \psi_i \rangle e_i \right) (\omega) = \psi(\omega).$$

Thus, the proof is complete.

(iii)  $\Rightarrow$  (ii) It is clear.

(i)  $\Rightarrow$  (iii) Let  $\{\phi_i\}_{i \in I}$  be an orthonormal basis for  $M$ . Let  $\Gamma = \{\Lambda_\omega S_\Lambda^{-1/2} \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$ , then  $T_\Gamma T_\Gamma^* = T_\Gamma^* T_\Gamma = I$ . If we take  $e_i = T_\Gamma \phi_i$ , for all  $i \in I$  then  $\{e_i\}_{i \in I}$  is an orthonormal basis for  $\mathcal{H}$  and

$$\sum_{i \in I} \|\phi_i(\omega)\|^2 = \sum_{j \in J_\omega} \|S_\Lambda^{-1/2} \Lambda_\omega^* e_{\omega_j}\|^2 < \infty.$$

*Proposition 2.5* — Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  and  $\Theta = \{\Theta_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be two continuous  $g$ -frames with representation  $\Lambda_\omega f = \sum_{i \in I} \langle f, e_i \rangle \psi_i(\omega)$  and  $\Theta_\omega f = \sum_{i \in I} \langle f, f_i \rangle \phi_i(\omega)$  for some  $\{\phi_i\}_{i \in I}$  and  $\{\psi_i\}_{i \in I}$  in  $\widehat{\mathcal{K}}$ , and for some orthonormal bases  $\{e_i\}_{i \in I}$  and  $\{f_i\}_{i \in I}$  for  $\mathcal{H}$ . Then  $\Lambda$  is a dual of  $\Theta$  if and only if

$$\langle \psi_i, \phi_j \rangle = \langle e_i, f_j \rangle, \quad i, j \in I.$$

In particular, if  $e_i = f_i$ , for all  $i \in I$ , then  $\Lambda$  is a dual of  $\Theta$  if and only if  $\{\psi_i\}_{i \in I}$  and  $\{\phi_i\}_{i \in I}$  are biorthogonal.

PROOF : For any  $f, g \in \mathcal{H}$  we have

$$\langle f, g \rangle = \sum_{i, j \in I} \langle f, e_i \rangle \langle f_j, g \rangle \langle e_i, f_j \rangle,$$

and

$$\begin{aligned} \int_{\Omega} \langle f, \Lambda_\omega^* \Theta_\omega g \rangle d\mu_\omega &= \int_{\Omega} \sum_{i, j \in I} \langle f, e_i \rangle \langle f_j, g \rangle \langle \psi_i(\omega), \phi_j(\omega) \rangle d\mu(\omega) \\ &= \sum_{i, j \in I} \langle f, e_i \rangle \langle f_j, g \rangle \langle \psi_i, \phi_j \rangle. \end{aligned}$$

Thus, the proof is completed. □

In the rest of this section we intend to generalize some results of [7] to continuous  $g$ -frame.

*Lemma 2.6* — Let  $(\Omega, \mu)$  be a measure space. Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  and  $\Theta = \{\Theta_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be two Parseval continuous  $g$ -frames. Then  $\text{Range}(T_\Theta^*) \subseteq \text{Range}(T_\Lambda^*)$  if and only if there exists an isometry  $U : \mathcal{H} \rightarrow \mathcal{H}$  such that  $\Theta_\omega = \Lambda_\omega U$  for a.e.  $\omega \in \Omega$ .

PROOF : Let  $\text{Range}(T_\Theta^*) \subseteq \text{Range}(T_\Lambda^*)$ .  $\text{Range}T_\Lambda^*$  is a closed subspace of  $\widehat{\mathcal{K}}$ . We take  $P = T_\Lambda^* T_\Lambda$ . So,  $\text{Range}(P) = \text{Range}(T_\Lambda^*)$ . Since  $\Lambda$  is a Parseval continuous  $g$ -frame, then  $P$  is an orthogonal projection from  $\widehat{\mathcal{K}}$  onto  $\text{Range}(T_\Lambda^*)$ . We consider  $U = T_\Lambda T_\Theta^*$ . Then

$$\|Uf\|^2 = \langle U^* U f, f \rangle = \langle T_\Theta P T_\Theta^* f, f \rangle = \|f\|^2, \quad f \in \mathcal{H}.$$

and

$$\langle U^* f, g \rangle = \langle T_\Theta T_\Lambda^* f, g \rangle = \int_{\Omega} \langle \Lambda_\omega f, \Theta_\omega g \rangle d\mu(\omega), \quad f, g \in \mathcal{H}.$$

Thus

$$\begin{aligned}
 \int_{\Omega} \|(\Lambda_{\omega}U - \Theta_{\omega})f\|^2 d\mu(\omega) &= \int_{\Omega} \|\Lambda_{\omega}U(f)\|^2 d\mu(\omega) - \int_{\Omega} \langle \Lambda_{\omega}U(f), \Theta_{\omega}f \rangle d\mu(\omega) \\
 &\quad - \int_{\Omega} \langle \Theta_{\omega}f, \Lambda_{\omega}U(f) \rangle d\mu(\omega) + \int_{\Omega} \|\Theta_{\omega}f\|^2 d\mu(\omega) \\
 &= \|Uf\|^2 - \langle U^*Uf, f \rangle - \langle Uf, Uf \rangle + \|f\|^2 \\
 &= \|Uf\|^2 - \|Uf\|^2 - \|Uf\|^2 + \|f\|^2 = 0.
 \end{aligned}$$

Hence,  $\Lambda_{\omega}Uf = \Theta_{\omega}f$  for a.e.  $\omega \in \Omega$  and  $f \in \mathcal{H}$ . The other implication is clear.  $\square$

*Proposition 2.7* — Let  $(\Omega, \mu)$  be a measure space. Let  $\Lambda = \{\Lambda_{\omega} \in B(\mathcal{H}, \mathcal{K}_{\omega}) : \omega \in \Omega\}$  and  $\Theta = \{\Theta_{\omega} \in B(\mathcal{H}, \mathcal{K}_{\omega}) : \omega \in \Omega\}$  be two Parseval continuous  $g$ -frames and  $\Lambda$  be a Riesz-type continuous  $g$ -frame. Then  $\Theta$  is Riesz-type if and only if there exists an unitary operator  $U : \mathcal{H} \rightarrow \mathcal{K}$  such that  $\Theta_{\omega}U = \Lambda_{\omega}$  for a.e.  $\omega \in \Omega$ .

PROOF : Let  $\Theta$  be Riesz-type, then  $Range(T_{\Lambda}^*) = Range(T_{\Theta}^*) = \widehat{\mathcal{K}}$ . By Lemma 2.6, there is a bounded operator  $U$  on  $\mathcal{H}$  such that  $U^*U = I_{\mathcal{H}}$  and  $\Theta_{\omega} = \Lambda_{\omega}U$  for a.e.  $\omega \in \Omega$  and hence  $T_{\Theta}^* = T_{\Lambda}^*U$ . Since both  $T_{\Lambda}^*$  and  $T_{\Theta}^*$  are invertible, it follows that  $U$  is a unitary operator. For the other implication, let  $U : \mathcal{H} \rightarrow \mathcal{K}$  be a unitary linear operator such that  $\Theta_{\omega} = \Lambda_{\omega}U$ , then  $T_{\Theta}^* = T_{\Lambda}^*U$  and so,  $Range T_{\Theta}^* = \widehat{\mathcal{K}}$ . By Theorem 1.9,  $\Theta$  is Riesz-type.  $\square$

*Proposition 2.8* — Let  $\Lambda = \{\Lambda_{\omega} \in B(\mathcal{H}, \mathcal{K}_{\omega}) : \omega \in \Omega\}$  be a Riesz-type continuous  $g$ -frame and  $\Theta = \{\Theta_{\omega} \in B(\mathcal{H}, \mathcal{K}_{\omega}) : \omega \in \Omega\}$  be a continuous  $g$ -frame. Then  $\Theta$  is a Riesz-type continuous  $g$ -frame if and only if  $\Lambda$  and  $\Theta$  are similar.

PROOF : It is obvious by Proposition 1.8 and Theorem 1.9.  $\square$

**Theorem 2.9** — Let  $\Lambda = \{\Lambda_{\omega} \in B(\mathcal{H}, \mathcal{K}_{\omega}) : \omega \in \Omega\}$  be a Riesz-type continuous  $g$ -frame and  $\Theta = \{\Theta_{\omega} \in B(\mathcal{H}, \mathcal{K}_{\omega}) : \omega \in \Omega\}$  be a continuous  $g$ -frame. Then the following conditions are equivalent:

(i)  $\Theta$  is a Riesz-type continuous  $g$ -frame.

(ii) There exists a constant  $M > 0$  such that for all  $\phi \in \widehat{\mathcal{K}}$

$$\|T_{\Lambda}\phi - T_{\Theta}\phi\|^2 \leq M \cdot \min\{\|T_{\Lambda}\phi\|^2, \|T_{\Theta}\phi\|^2\}. \quad (2.1)$$

PROOF : (i)  $\Rightarrow$  (ii) By Proposition 2.8, there is an invertible bounded operator  $U : \mathcal{H} \rightarrow \mathcal{H}$  such that  $\Theta_\omega = \Lambda_\omega U$  for a.e.  $\omega \in \Omega$ . For any  $g \in \mathcal{H}$  and  $\phi \in \widehat{\mathcal{K}}$  we have

$$\begin{aligned} \langle U^* T_\Lambda \phi, g \rangle &= \langle T_\Lambda \phi, U g \rangle = \int_{\Omega} \langle U^* \Lambda_\omega^* \phi(\omega), g \rangle d\mu(\omega) \\ &= \int_{\Omega} \langle \Theta_\omega^* \phi(\omega), g \rangle d\mu(\omega) = \langle T_\Theta \phi, g \rangle. \end{aligned}$$

Then  $T_\Theta = U^* T_\Lambda$  and so

$$\begin{aligned} \|T_\Lambda \phi - T_\Theta \phi\|^2 &= \|T_\Lambda \phi - U^* T_\Lambda \phi\|^2 \leq \|I - U^*\|^2 \|T_\Lambda \phi\|^2 \\ &\leq (1 + \|U\|)^2 \|T_\Lambda \phi\|^2. \end{aligned}$$

Similarity

$$\|T_\Lambda \phi - T_\Theta \phi\|^2 \leq (1 + \|U^{-1}\|)^2 \|T_\Theta \phi\|^2.$$

Then we have

$$\|T_\Lambda \phi - T_\Theta \phi\|^2 \leq M \cdot \min\{\|T_\Lambda \phi\|^2, \|T_\Theta \phi\|^2\}$$

where  $M = \max\{(1 + \|U\|)^2, (1 + \|U^{-1}\|)^2\}$ .

(ii)  $\Rightarrow$  (i) Since  $T_\Lambda$  is invertible, then for any  $f \in \mathcal{H}$  there exists an unique  $\phi \in \widehat{\mathcal{K}}$  such that  $T_\Lambda \phi = f$ . Let us consider well defined bounded operator  $U : \mathcal{H} \rightarrow \mathcal{H}$  by

$$U f = T_\Theta \phi, \quad f \in \mathcal{H}.$$

By the inequality (2.1),  $U$  is injective. On the other hand, since  $T_\Theta$  is surjective, then  $U$  is surjective. So,  $U$  is invertible. For any  $\phi \in \widehat{\mathcal{K}}$  and  $g \in \mathcal{H}$  we have

$$\begin{aligned} \langle \phi, \{(\Theta_\omega - \Lambda_\omega U^*)g\}_{\omega \in \Omega} \rangle &= \int_{\Omega} \langle \phi(\omega), (\Theta_\omega - \Lambda_\omega U^*)g \rangle d\mu(\omega) \\ &= \int_{\Omega} \langle \Theta_\omega^* \phi(\omega), g \rangle d\mu(\omega) - \int_{\Omega} \langle \Lambda_\omega^* \phi(\omega), U^* g \rangle d\mu(\omega) \\ &= \langle T_\Theta \phi, g \rangle - \langle T_\Lambda \phi, U^* g \rangle \\ &= \langle U T_\Lambda \phi, g \rangle - \langle U T_\Lambda \phi, g \rangle = 0 \end{aligned}$$

Thus,  $\Theta_\omega = \Lambda_\omega U^*$  for a.e.  $\omega \in \Omega$ . Therefore, by Proposition 2.8,  $\Theta$  is Riesz-type.  $\square$

3. STABILITY OF DUALS OF CONTINUOUS  $G$ -FRAMES

In this section we study stability of duals of continuous  $g$ -frames.

*Lemma 3.1* —  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be a continuous  $g$ -frame and  $\Theta = \{\Theta_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  is a dual of  $\Lambda$ . Then there exists a operator  $S \in B(\mathcal{H}, \widehat{\mathcal{K}})$  such that  $T_\Lambda S = 0$  and  $\Theta_\omega f = (Sf)(\omega) + \Lambda_\omega S_\Lambda^{-1} f$ , for all  $\omega \in \Omega$  and  $f \in \mathcal{H}$ .

PROOF : Let us consider  $S : \mathcal{H} \rightarrow \widehat{\mathcal{K}}$ , by

$$(Sf)(\omega) = \Theta_\omega f - \Lambda_\omega S_\Lambda^{-1} f, \quad f \in \mathcal{H}, \omega \in \Omega.$$

Then for all  $f \in \mathcal{H}$ ,

$$\begin{aligned} \|Sf\| &= \left( \int_\Omega \|(Sf)(\omega)\|^2 d\mu(\omega) \right)^{1/2} \\ &\leq \left( \int_\Omega \|\Theta_\omega f\|^2 d\mu(\omega) \right)^{1/2} + \left( \int_\Omega \|\Lambda_\omega S_\Lambda^{-1} f\|^2 d\mu(\omega) \right)^{1/2} \\ &\leq \left( \sqrt{B_\Theta} + \frac{1}{\sqrt{A_\Lambda}} \right) \|f\|. \end{aligned}$$

Thus,  $S$  is bounded. On the other hand, for any  $f, g \in \mathcal{H}$ ,

$$\begin{aligned} \langle T_\Lambda S f, g \rangle &= \int_\Omega \langle \Lambda_\omega^* (Sf)(\omega), g \rangle d\mu(\omega) \\ &= \int_\Omega \langle \Lambda_\omega^* \Theta_\omega f, g \rangle d\mu(\omega) - \int_\Omega \langle \Lambda_\omega^* \Lambda_\omega S_\Lambda^{-1} f, g \rangle d\mu(\omega) \\ &= \langle f, g \rangle - \langle f, g \rangle = 0. \end{aligned}$$

So,  $T_\Lambda S = 0$ . □

*Theorem 3.2* — Let  $\Lambda = \{\Lambda_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  and  $\Theta = \{\Theta_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be two continuous  $g$ -frames. Also, let  $\hat{\Lambda} = \{\hat{\Lambda}_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  be a fixed dual for  $\Lambda$ . If  $\Lambda - \Theta$  is a continuous  $g$ -Bessel family with sufficiently small bound  $\varepsilon > 0$ , then there exists a dual  $\hat{\Theta}$  for  $\Theta$  such that  $\hat{\Lambda} - \hat{\Theta}$  is also continuous  $g$ -Bessel.

PROOF : By Lemma 3.1, there exist  $S \in B(\mathcal{H}, \widehat{\mathcal{K}})$  such that  $T_\Lambda S = 0$  and

$$\hat{\Lambda}_\omega f = (Sf)(\omega) + \Lambda_\omega S_\Lambda^{-1} f, \quad f \in \mathcal{H}, \omega \in \Omega.$$

Let  $M = \{M_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$  such that

$$M_\omega f = (Sf)(\omega) + \Theta_\omega S_\Theta^{-1} f, \quad f \in \mathcal{H}.$$

It is easy to see that  $M$  is a continuous  $g$ -Bessel family with bound  $(\frac{1}{\sqrt{A_\Theta}} + \|S\|)^2$ . For  $f, g \in \mathcal{H}$  we have

$$\begin{aligned}
\langle f - T_\Theta T_M^* f, g \rangle &= \langle f, g \rangle - \int_\Omega \langle \Theta_\omega^*(T_M^* f)(\omega), g \rangle d\mu(\omega) \\
&= \langle f, g \rangle - \int_\Omega \langle \Theta_\omega^* M_\omega f, g \rangle d\mu(\omega) \\
&= \langle f, g \rangle - \int_\Omega \langle \Theta_\omega^*(Sf)(\omega), g \rangle d\mu(\omega) - \int_\Omega \langle \Theta_\omega^* \Theta_\omega S_\Theta^{-1} f, g \rangle d\mu(\omega) \\
&= \langle f, g \rangle - \langle T_\Theta Sf, g \rangle - \langle f, g \rangle \\
&= -\langle T_\Theta Sf, g \rangle.
\end{aligned}$$

Thus,  $f - T_\Theta T_M^* f = -T_\Theta Sf$ , for all  $f \in \mathcal{H}$ . Hence

$$\begin{aligned}
\|f - T_\Theta T_M^* f\| &= \|T_\Theta Sf\| = \|T_\Theta Sf - T_\Lambda Sf\| \\
&\leq \|T_\Theta - T_\Lambda\| \|S\| \|f\| \\
&\leq \sqrt{\varepsilon} \|S\| \|f\|,
\end{aligned}$$

Therefore, for all  $f \in \mathcal{H}$ ,  $\|I_H - T_\Theta T_M^*\| \leq \sqrt{\varepsilon} \|S\|$  and thus,  $T_\Theta T_M^*$  is invertible because  $\varepsilon$  is sufficiently small. Hence,  $\hat{\Theta} = \{\hat{\Theta}_\omega \in B(\mathcal{H}, \mathcal{K}_\omega) : \omega \in \Omega\}$ ,  $\hat{\Theta}_\omega = M_\omega (T_\Theta T_M^*)^{-1}$  is a dual for  $\Theta$ . Because

$$\begin{aligned}
\int_\Omega \langle \hat{\Theta}_\omega f, \Theta_\omega g \rangle d\mu(\omega) &= \int_\Omega \langle (T_M^* (T_\Theta T_M^*)^{-1} f)(\omega), \Theta_\omega g \rangle d\mu(\omega) \\
&= \int_\Omega \langle T_\Theta T_M^* (T_\Theta T_M^*)^{-1} f, g \rangle d\mu(\omega) \\
&= \langle f, g \rangle.
\end{aligned}$$

And we have

$$\begin{aligned}
\|S_\Lambda - S_\Theta\| &= \|T_\Lambda T_\Lambda^* - T_\Lambda T_\Theta^* + T_\Lambda T_\Theta^* - T_\Theta T_\Theta^*\| \\
&\leq \|T_\Lambda - T_\Theta\| (\|T_\Lambda\| + \|T_\Theta\|) \\
&\leq \sqrt{\varepsilon} (\sqrt{B_\Lambda} + \sqrt{B_\Theta}).
\end{aligned} \tag{3.1}$$

And by  $\tilde{\Lambda}(f) = (Sf)(\omega) + \Lambda_\omega S_\Lambda^{-1} f$  and  $M_\omega(f) = (Sf)(\omega) + \Theta_\omega S_\Theta^{-1} f$ , we have

$$\begin{aligned}
\langle T_\Lambda \phi - T_M \phi, f \rangle &= \int_\Omega \langle \phi(\omega), \hat{\Lambda}_\omega f \rangle d\mu(\omega) - \int_\Omega \langle \phi(\omega), M_\omega f \rangle d\mu(\omega) \\
&= \int_\Omega \langle \phi(\omega), \Lambda_\omega S_\Lambda^{-1} f - \Theta_\omega S_\Theta^{-1} f \rangle d\mu(\omega) \\
&= \langle T_\Lambda \phi, S_\Lambda^{-1} f \rangle - \langle T_\Theta \phi, S_\Theta^{-1} f \rangle \\
&= \langle T_\Lambda \phi, (S_\Lambda^{-1} - S_\Theta^{-1}) f \rangle + \langle (T_\Lambda - T_\Theta) \phi, S_\Theta^{-1} f \rangle,
\end{aligned}$$

Hence, by inequality (3.1) we have

$$\begin{aligned}
 \|T_{\hat{\Lambda}}\phi - T_M\phi\| & \leq \|T_{\Lambda}\phi\| \|S_{\Lambda}^{-1} - S_{\Theta}^{-1}\| + \|T_{\Lambda} - T_{\Theta}\| \|\phi\| \|S_{\Theta}^{-1}\| \\
 & \leq \|T_{\Lambda}\| \|\phi\| \|S_{\Lambda}^{-1}\| \|S_{\Theta} - S_{\Lambda}\| \|S_{\Theta}^{-1}\| + \frac{1}{A_{\Theta}} \sqrt{\varepsilon} \|\phi\| \\
 & \leq \frac{1}{A_{\Lambda}} \frac{1}{A_{\Theta}} \sqrt{\varepsilon} \sqrt{B_{\Lambda}} (\sqrt{B_{\Lambda}} + \sqrt{B_{\Theta}}) \|\phi\| + \frac{1}{A_{\Theta}} \sqrt{\varepsilon} \|\phi\| \\
 & = \frac{\sqrt{\varepsilon} (A_{\Lambda} + B_{\Lambda} + \sqrt{B_{\Lambda} B_{\Theta}})}{A_{\Lambda} A_{\Theta}} \|\phi\|.
 \end{aligned} \tag{3.2}$$

If we take  $T = (T_{\Theta} T_M^*)^{-1}$ , then

$$\|T\| \leq \frac{1}{1 - \|I_H - T^{-1}\|} \leq \frac{1}{1 - \sqrt{\varepsilon} S},$$

and so

$$\|I_H - T\| \leq \|T\| \|I_H - T^{-1}\| \leq \frac{\sqrt{\varepsilon} \|S\|}{1 - \sqrt{\varepsilon} \|S\|}. \tag{3.3}$$

Consequently, by inequalities (3.2) and (3.3)

$$\begin{aligned}
 \|T_{\hat{\Lambda}}\phi - T_{\Theta}\phi\| & = \sup_{\|f\|=1} |\langle T_{\hat{\Lambda}}\phi - T_{\Theta}\phi, f \rangle| \\
 & = \sup_{\|f\|=1} |\langle (I_H - T^*)T_{\hat{\Lambda}}\phi + T^*(T_{\hat{\Lambda}} - T_M)\phi, f \rangle| \\
 & \leq \|I_H - T^*\| \|T_{\hat{\Lambda}}\| \|\phi\| + \|T^*\| \|(T_{\hat{\Lambda}} - T_M)\phi\| \\
 & \leq \frac{\sqrt{\varepsilon} \|\phi\|}{1 - \sqrt{\varepsilon} \|S\|} (\|S\| \sqrt{B_{\hat{\Lambda}}} + \frac{A_{\Lambda} + B_{\Lambda} + \sqrt{B_{\Lambda} B_{\Theta}}}{A_{\Lambda} A_{\Theta}}). \square
 \end{aligned}$$

REFERENCES

1. M. R. Abdollahpour and M. H. Faroughi, *Continuous G-Frames in Hilbert Spaces*, Southeast Asian Bulletin of Mathematics, **32** (2008), 1-19.
2. S. T. Ali, J.-P. Antoine and J.-P. Gazeau, Continuous frames in Hilbert space, *Annals of Physics*, **222** (1993), 1-37.
3. O. Christensen, *An introduction to frames and Riesz bases*, Birkhauser, Boston (2003).

4. R. J. Duffin and A. C. Schaeffer, A class of nonharmonic Fourier series, *Transactions of the American Mathematical Society*, **72** (1952), 341-366.
5. J.-P. Gabardo and D. Han, Frames associated with measurable space, *Advances in Computational Mathematics*, **18** (2003), 127-147.
6. W. Sun,  $G$ -frames and  $g$ -Riesz bases, *Journal of Mathematical Analysis and Applications*, **322** (2006), 437-452.
7. Z.-Q. Xiang, *New characterizations of Riesz-type frames and stability of alternate duals of continuous frames*, *Advances in Mathematical Physics* 2013 (2013). Article ID 298982, 11 pages. doi: 10.1155/2013/298982.