

ON STABILITY OF DERIVO-PERIODIC SOLUTIONS OF NON-HOLONOMIC SYSTEMS

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The non-holonomic periodic perturbation of a holonomic system is considered. A general condition and an expression for stability criteria of the derivo-periodic solution are given.

In this paper we consider the perturbed system containing a small parameter while it is assumed that the unperturbed system is holonomic, has a D -periodic solution, the perturbation is non-holonomic and is controllably periodic. The stability criterion was studied by Farkas (1971, 1972) and El-Owaidy (1975). Here we shall report further studies in a general case. For the sake of convenience, some results of Farkas and El-Owaidy are summarized in section 1.

§1. Consider the system

$$\frac{dx}{dt} = f(x) + \mu g\left(\frac{t}{\tau}, x, \mu, \tau\right) = \tilde{F}\left(\frac{t}{\tau}, x, \mu, \tau\right) \quad \dots(1)$$

where x, f, g are n -dimensional vectors and t, μ, τ are real scalars and the function on the right-hand side is analytic in the region $I_t \times \Omega \times I_\mu \times I_\tau$ where

$$I_t = \{t : -\infty < t < +\infty\},$$

Ω is an open and connected region in n -dimensional space of x ,

$$I_\mu = \{\mu : |\mu| < \alpha\}, \quad \alpha > 0,$$

$$I_\tau = \{\tau : |\tau - \tau_0| < \beta\}, \quad 0 < \beta < \tau_0.$$

Assume that the function

$$\tilde{F}\left\{\frac{t}{\tau}, x, \mu, \tau\right\}$$

is periodic in t with period $\tau \in I_\tau$ and is also periodic in the vector x with vector period $a \tau$.

Definition — We say that the continuously differentiable vector function $\varphi(t)$ is D -periodic with period τ if its derivative is periodic with least period (cf. Farkas 1971).

Together with (1) we consider the unperturbed holonomic system

$$\frac{dx}{dt} = f(x) \tag{2}$$

It will be assumed that the system (2) has a non-constant D -periodic solution

$$p(t) = \gamma(t) + a^0 t \quad (\text{such that } \gamma(t + \tau_0) = \gamma(t)),$$

with period $\tau_0 > 0$, coefficient vector a^0 . The first variational system of (2) corresponding to $p(t)$ is

$$\frac{dy}{dt} = f'_x(p(t)) y \tag{3}$$

and its fundamental matrix solution is denoted by $Y(t)$. It is assumed that $n - 1$ characteristic multipliers of system (3) are in modulus less than one.

It was proved by Farkas (1971) that the system (1) has a unique D -periodic solution $\varphi(t, \mu, \theta)$ with period $\tau(\mu, \theta)$. The first variational system of (1) corresponding to $\varphi(t, \mu, \theta)$ is

$$\frac{dy}{dt} = \left[f'_x(\varphi(t, \mu, \theta)) + \mu g'_x \left(\frac{t}{\tau}, \varphi(t, \mu, \theta), \mu, \tau(\mu, \theta) \right) \right] Y. \tag{4}$$

and its fundamental matrix solution is denoted by $Y(t; \mu, \theta)$, for which $Y(0, \mu, \theta) = U$ (U : the unit matrix) holds, and by $C(\mu, \theta) = Y(\tau, \mu, \theta)$, the characteristic matrix of (4) for which $C(0, 0) = Y(\tau_0, 0, 0) = Y(\tau_0)$ holds. Let $\lambda(\mu, \theta)$ also denote the characteristic multiplier of $C(\mu, \theta)$ for which $\lambda(0, 0) = 1$ holds.

It was proved by Farkas (1972) that the D -periodic solution $\varphi(t; \mu, \theta)$ of (1) is asymptotically stable if $\mu \lambda'_\mu(0, 0) < 0$. Also if $\lambda'_\mu(0, 0) = 0$ it was proved by the author (El-Owaidy 1975) that the solution is asymptotically stable if $\lambda''_{\mu\mu}(0, 0) < 0$.

§2. Now we shall study the stability of the D -periodic solution of the system (1) in the general case:

Theorem 1 — Under the assumptions stated above, if 1 is a simple characteristic multiplier of (3) and the remaining $(n - 1)$ characteristic multipliers are in modulus less than 1 and

$$\left. \begin{aligned} \lambda_{\mu \dots \mu}^{(r)}(0, 0) &= 0, \quad r = 1, 2, \dots, k - 1 \\ \lambda_{\mu \dots \mu}^{(k)}(0, 0) &< 0, \quad k \text{ even} \end{aligned} \right\} \tag{5}$$

then there exists $\rho > 0$ such that for

$$0 < |\mu| < \rho, \quad \theta = 0,$$

the D -periodic solution $\varphi(t, \mu, 0)$ of system (1) is asymptotically stable.

PROOF : The proof is analogous to that of Theorem 1 (cf. El-Owaidy 1975) and should, therefore, be omitted here.

It should be noted that if

$$\lambda_{\mu \dots \mu}^{(r)}(0, 0) = 0, \quad r = 1, 2, \dots, k - 1,$$

$$\lambda_{\mu \dots \mu}^{(k)}(0, 0) > 0,$$

then the D -periodic solution is unstable.

Since the characteristic matrix $C(\mu, \theta)$ is an analytic function of its arguments, it can be expanded for fixed θ in powers of μ , i.e.

$$C(\mu, \theta) = C_0(\theta) + \mu C_1(\theta) + \mu^2 C_2(\theta) + \dots \\ \dots + \mu^k C_k(\theta) + R(\mu, \theta). \tag{6}$$

where R is an analytic function.

Let the characteristic polynomial of $C(\mu, \theta)$ be denoted by

$$(-1)^n d(\lambda, \mu, \theta) = \det [C(\mu, \theta) - \lambda U]. \tag{7}$$

Using Poincaré's method we can give an effective form for the stability condition $\lambda_{\mu \dots \mu}^{(k)}(0, 0)$ of Theorem 1.

Theorem 2 — Under the condition of Theorem 1

$$\lambda_{\mu \dots \mu}^{(k)}(0, 0) = \frac{(-1)^{n-1} (K!)}{d_\lambda^n(1, 0, 0)} \left\{ \sum_{\substack{i_1, i_2, \dots, i_k=1 \\ i_1 \neq i_2 \neq \dots \neq i_k}}^n \det M_{(i_1, i_2, \dots, i_k)} \right. \\ + \sum_{\substack{i_1, i_2, \dots, i_{k-1}=1 \\ i_1 \neq i_2 \neq \dots \neq i_{k-1}}}^n \det M_{(i_1, i_2, i_{k-1})} + \sum_{\substack{i_1, i_2, \dots, i_j=1 \\ i_1 \neq i_2 \neq \dots \neq i_j}}^n \det (M_{i_1, i_2, \dots, i_j}) \\ \left. + \sum_{\substack{i_1, i_2=1 \\ i_1 \neq i_2}}^n \det M_{(i_1, i_2)} + \sum_{i_1=1}^n \det M_{(i_1)} \right. \tag{8}$$

where

$$\begin{aligned}
 & M_{(i_1, i_2, \dots, i_k)} \quad , \quad M_{(i_1, i_2, \dots, i_{k-1})} \quad , \quad \dots \quad , \quad M_{(i_1, i_2, \dots, i_j)} \\
 & = \left| \begin{array}{c} c_1^0 - u_1 \\ \dots \dots \dots \\ c_{i_1-1}^0 - u_{i_1-1} \\ \\ c_{i_1}^1 \\ \\ c_{i_1+1}^0 - u_{i_1+1} \\ \dots \dots \dots \\ c_{i_2-1}^0 - u_{i_2-1} \\ \\ c_{i_2}^1 \\ \\ c_{i_2+1}^0 - u_{i_2+1} \\ \dots \dots \dots \\ c_{i_k-1}^0 - u_{i_k-1} \\ \\ c_{i_k}^1 \\ \\ c_{i_k+1}^0 - u_{i_k+1} \\ \dots \dots \dots \\ c_n^0 - u_n \end{array} \right| = \left| \begin{array}{c} c_1^0 - u_1 \\ \dots \dots \dots \\ c_{i_1-1}^0 - u_{i_1-1} \\ \\ c_{i_1}^1 \\ \\ c_{i_1+1}^0 - u_{i_1+1} \\ \dots \dots \dots \\ c_{i_2-1}^0 - u_{i_2-1} \\ \\ c_{i_2}^1 \\ \\ c_{i_2+1}^0 - u_{i_2+1} \\ \dots \dots \dots \\ c_{i_{k-1}-1}^0 - u_{i_{k-1}-1} \\ \\ c_{i_{k-1}}^2 \\ \\ c_{i_{k-1}+1}^0 - u_{i_{k-1}+1} \\ \dots \dots \dots \\ c_n^0 - u_n \end{array} \right| = \left| \begin{array}{c} c_1^0 - u_1 \\ \dots \dots \dots \\ c_{i_1-1}^0 - u_{i_1-1} \\ \\ c_{i_1}^{r_1} \\ \\ c_{i_1+1}^0 - u_{i_1+1} \\ \dots \dots \dots \\ c_{i_2-1}^0 - u_{i_2-1} \\ \\ c_{i_2}^{r_2} \\ \\ c_{i_2+1}^0 - u_{i_2+1} \\ \dots \dots \dots \\ c_{i_j-1}^0 - u_{i_j-1} \\ \\ c_{i_j}^{k - \sum_{s=1}^{j-1} r_s} \\ \\ c_{i_j+1}^0 - u_{i_j+1} \\ \dots \dots \dots \\ c_n^0 - u_n \end{array} \right|
 \end{aligned}$$

$$\begin{aligned}
 M_{(i_1, i_2)} & = \left| \begin{array}{c} c_1^0 - u_1 \\ \dots \dots \dots \\ c_{i_1-1}^0 - u_{i_1-1} \\ \\ c_{i_1}^1 \\ \\ c_{i_1+1}^0 - u_{i_1+1} \\ \dots \dots \dots \\ c_{i_2-1}^0 - u_{i_2-1} \\ \\ c_{i_2}^{k-1} \\ \\ c_{i_2+1}^0 - u_{i_2+1} \\ \dots \dots \dots \\ c_n^0 - u_n \end{array} \right| \qquad M_{(i_1)} = \left| \begin{array}{c} c_1^0 - u_1 \\ c_2^0 - u_2 \\ \dots \dots \dots \\ c_{i_1-1}^0 - u_{i_1-1} \\ \\ c_{i_1}^k \\ \\ c_{i_1+1}^0 - u_{i_1+1} \\ \dots \dots \dots \\ c_n^0 - u_n \end{array} \right|
 \end{aligned}$$

...(9)

and $c_j^0, c_j^1, c_j^2, \dots, c_j^k$ and u_j are the j th row vectors of the matrices:

$$C_0(0), C_1(0), C_2(0), \dots, C_k(0) \text{ and } U, \text{ respectively, } r_s \geq 1, K - \sum_{s=1}^{j-1} r_s > 0.$$

PROOF: Splitting up the determinant given by (7) by terms in its last row vector using the expansion (6) to a sum of $(K + 1)$ determinants we obtain

$$(-1)^n d(\lambda, u, \theta) = \det \begin{vmatrix} c_1^0 - \lambda u_1 + \mu c_1^1 + \mu^2 c_1^2 + \dots + \mu^k c_1^k + \mu^{k+1} r_1 \\ c_2^0 - \lambda u_2 + \mu c_2^1 + \mu^2 c_2^2 + \dots + \mu^k c_2^k + \mu^{k+1} r_2 \\ \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \\ c_{n-1}^0 - \lambda u_{n-1} + \mu c_{n-1}^1 + \mu^2 c_{n-1}^2 + \dots + \mu^k c_{n-1}^k + \mu^{k+1} r_{n-1} \\ c_n^0 - \lambda u_n \end{vmatrix} \\
 + \mu \det \begin{vmatrix} c_1^0 - \lambda u_1 + \mu c_1^1 + \mu^2 c_1^2 + \dots + \mu^k c_1^k + \mu^{k+1} r_1 \\ c_2^0 - \lambda u_2 + \mu c_2^1 + \mu^2 c_2^2 + \dots + \mu^k c_2^k + \mu^{k+1} r_2 \\ \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \\ c_{n-1}^0 - \lambda u_{n-1} + \mu c_{n-1}^1 + \mu^2 c_{n-1}^2 + \dots + \mu^k c_{n-1}^k + \mu^{k+1} r_{n-1} \\ c_n^1 \end{vmatrix} + \dots \\
 + \mu^K \det \begin{vmatrix} c_1^0 - \lambda u_1 + \mu c_1^1 + \mu^2 c_1^2 + \dots + \mu^k c_1^k + \mu^{k+1} r_1 \\ c_2^0 - \lambda u_2 + \mu c_2^1 + \mu^2 c_2^2 + \dots + \mu^k c_2^k + \mu^{k+1} r_2 \\ \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \\ c_{n-1}^0 - \lambda u_{n-1} + \mu c_{n-1}^1 + \mu^2 c_{n-1}^2 + \dots + \mu^k c_{n-1}^k + \mu^{k+1} r_{n-1} \\ c_n^k \end{vmatrix} + \mu^{k+1} \det \begin{vmatrix} r_1 \\ r_2 \\ r_3 \\ \dots \\ \dots \\ r_{n-1} \\ r_n \end{vmatrix}$$

Also splitting up the resulting determinants by terms in the $(n - 1)$ th, $(n - 2)$ th, ... and the first rows, and by putting $\lambda = 1, \theta = 0$ in the resulting determinants we obtain

$$(-1)^n d(1, \mu, 0) = \det [C_0(0) - U] + \mu N_1 + \mu^2 N_2 \\
 + \dots + \mu^k N_k + \mu^{k+1} R_{k+1}(u, 0) \dots (10)$$

where

$$N_1 = \sum_{i_1=1}^n \det \begin{pmatrix} c_1^0 - u_1 \\ c_2^0 - u_2 \\ \dots \dots \dots \\ c_{i_1-1}^0 - u_{i_1-1} \\ c_{i_1}^1 \\ c_{i_1+1}^0 - u_{i_1+1} \\ \dots \dots \dots \\ \dots \dots \dots \\ c_n^0 - u_n \end{pmatrix}, N_2 = \sum_{\substack{i_1, i_2=1 \\ i_1 \neq i_2}}^n \begin{pmatrix} c_1^0 - u_1 \\ c_2^0 - u_2 \\ \dots \dots \dots \\ c_{i_1-1}^0 - u_{i_1-1} \\ c_{i_1}^1 \\ c_{i_1+1}^0 + u_{i_1+1} \\ \dots \dots \dots \\ c_{i_2-1}^0 - u_{i_2-1} \\ c_{i_2}^1 \\ c_{i_2+1}^0 - u_{i_2+2} \\ \dots \dots \dots \\ c_n^0 - u_n \end{pmatrix} + \sum_{i_1=1}^n \det \begin{pmatrix} c_1^0 - u_1 \\ c_2^0 - u_2 \\ \dots \dots \dots \\ c_{i_1-1}^0 - u_{i_1-1} \\ c_{i_1}^2 \\ c_{i_1+1}^0 - u_{i_1+1} \\ \dots \dots \dots \\ \dots \dots \dots \\ c_n^0 - u_n \end{pmatrix}$$

$$N_k = \sum_{\substack{i_1, i_2, \dots, i_k=1 \\ i_1 \neq i_2 \neq \dots \neq i_k}}^n \det M_{(i_1, i_2, \dots, i_k)} + \dots + \sum_{\substack{i_1, i_2=1 \\ i_1 \neq i_2}}^n \det M_{(i_1, i_2)} + \sum_{i_1=1}^n \det M_{(i_1)}$$

and $M_{(i_1, i_2, \dots, i_k)}, \dots, M_{(i_1, i_2)}, M_{(i_1)}$ are defined by (9).

Since 1 is a simple root of the polynomial $d(1; 0, 0)$, i.e. $d(1, 0, 0) = 1, d'_\lambda(1, 0, 0) \neq 0$ and since $\lambda(\mu, 0)$ is an analytic function in a neighbourhood of $(0, 0)$ such that $\lambda(0, 0) = 1$, hence $\lambda(\mu, 0)$ can be expressed from the equation $d(\lambda; \mu, 0)$ as

$$\lambda(\mu, 0) = 1 + \mu \lambda'_\mu(0, 0) + \frac{\mu^2}{2!} \lambda''_{\mu\mu}(0, 0) + \dots + \frac{\mu^k}{K!} \lambda^{(K)}_{\mu \dots \mu}(0, 0) + O(\mu^k) \dots(11)$$

$\lambda^{(K)}_{\mu \dots \mu}(0, 0)$ can be obtained from the relation $d(\lambda; \mu, 0)$ by differentiating K times with respect to μ and taking into consideration $\lambda^{(r)}_{\mu \dots \mu}(0, 0) = 0, r = 1, 2, \dots, K - 1$, and by putting $\lambda = 1, \mu = 0$ we obtain

$$\lambda^{(K)}_{\mu \dots \mu}(0, 0) = -d^{(K)}_{\mu \mu \dots \mu}(1, 0, 0)/d'_\lambda(1; 0, 0). \dots(12)$$

If we differentiate (10) K times with respect to μ , put $\mu = 0$, using (12) we obtain (8); this completes the proof.

To use the expression (8) we need to calculate the matrices $C^0(0)$, $C^1(0)$, ..., $C^K(0)$, which can be obtained in the same manner as for $C^1(0)$ (cf. Farkas 1972) and $C^2(0)$ (cf. El-Owaidy 1975), since the computations for these matrices are in general very long and tedious.

Notes:

- (1) It is clear that the sum of the upper indices of all the row vectors must be K in all the above determinants.
- (2) The results obtained here are closely related to those of Loud (cf. Loud 1959) though we obtained a general expression for stability criteria and the problem and approach are different.
- (3) We studied here the case when the parameter $\theta = 0$. If $\theta \neq 0$ then many critical cases arise (cf. Farkas 1973).
- (4) If the periodic solution of (3) is not isolated [i.e. 1 is not a simple characteristic multiplier of (3)] the above stability criteria does not hold and needs more investigation.

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