

## ON THE PROPAGATION OF ELASTIC WAVES IN THE HALF-PLANE

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In a previous investigation (El-Dewik 1975) the problem of propagation of waves in an elastic half-plane has been solved on the assumption that the half-plane is occupied by an ideal elastic medium. It was also assumed that there exists a load perpendicular to the boundary of the half-plane and propagates on the boundary with a constant speed  $D$ . The assumption further involved that the displacements are in the direction of the load, whereas the lateral displacements are neglected. However it was mentioned (El-Dewik 1975) that the lateral displacements could be taken into account assuming that they satisfy a similar wave equation to that of the vertical displacement.

The present work is intended as a further contribution in which the lateral displacements are taken into consideration.

The wave equations of the vertical and lateral displacements are given by (see El-Dewik 1975)

$$\frac{\partial^2 W}{\partial t^2} = a^2 \left( \frac{\partial^2 W}{\partial x^2} + \frac{\partial^2 W}{\partial y^2} \right) \quad \dots(1)$$

$$\frac{\partial^2 V}{\partial t^2} = b^2 \left( \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} \right) \quad \dots(2)$$

where  $a$  is the velocity of longitudinal wave and  $b$  the velocity of later wave.

These equations will now be solved under the initial conditions:

$$\text{at } t = 0 \quad V = W = 0, \quad V_t = W_t = 0 \quad \dots(3)$$

and the surface conditions :

$$\left. \begin{aligned} \delta_{xy} &= 0 \quad \text{On the boundary } y = 0 \\ \delta_{yy} &= \delta_0 \quad \text{at } y = 0, \quad -Dt \leq x \leq Dt \\ \delta_{yy} &= 0 \quad \text{at } 0, \quad -at < x \leq -Dt, \quad Dt < x < at. \end{aligned} \right\} \quad \dots(4)$$

The solution of the problem may be written in the form:

$$W = \iint_{\sigma_1} \frac{C_1(\xi, \tau) d\xi d\tau}{[(l_1 - \tau)^2 - ((x - \xi)^2 - y^2)]^{1/2}}, \quad l_1 = at \quad \dots(5)$$

$$V = \iint_{\sigma_2} \frac{C_2(\xi, \tau) d\xi d\tau}{[(l_2 - \tau)^2 - (x - \xi)^2 - y^2]^{1/2}}, \quad l_2 = bt \quad \dots(6)$$

where

$\delta_1$  = a region in the plane  $\xi, \tau$  which is limited by hyperplolid

$$\tau = l_1 - [(x - \xi)^2 - y^2]^{1/2} \quad \dots(7)$$

and the two straight lines

$$\xi = \pm M_1\tau, \quad M_1 = \frac{D}{a} \quad \dots(8)$$

as shown in Fig. 1.

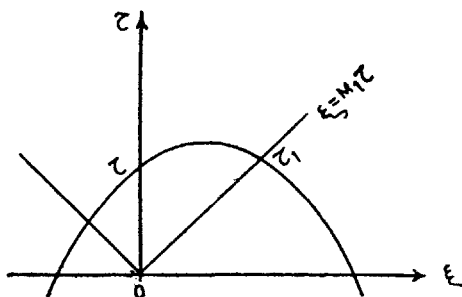


FIG. 1.

$\delta_2$  is similar to  $\delta_1$  by exchanging  $l_1$  by  $l_2$  and  $M_1$  by  $M_2$ .

It is easy to prove that the expressions (5) and (6) satisfy the wave equations (1) and (2) and the following relations may follow:

$$\left. \begin{aligned} \left( \frac{\partial W}{\partial y} \right)_{y=0} &= -\pi C_1(x, l) \\ \left( \frac{\partial V}{\partial y} \right)_{y=0} &= -\pi C_2(x, l). \end{aligned} \right\} \quad \dots(9)$$

Using the boundary conditions and Hook's law, the relation (9) may be written in the form:

$$(\lambda + 2\mu) \left( -\pi C_1 \right) + \left( \frac{\partial V}{\partial x} \right)_{y=0} = \delta_0 \quad \dots(10)$$

$$-\pi C_2 + \left( \frac{\partial W}{\partial x} \right)_{y=0} = 0. \quad \dots(11)$$

As it is clear from (10) and (11), in order to determine  $C_1$  and  $C_2$  we get two pairs of integral equations. The solution of this set of equations may be reached using the successive iteration.

As a first approximation we put  $V = 0$ , then from (10) we get

$$C_1(x, l) = - \frac{\delta_0}{(\lambda + 2\mu)}. \quad \dots(12)$$

Accordingly from (5) an expression for  $W$  may be obtained in the form:

$$W = - \frac{\delta_0}{\pi(\lambda + 2\mu)} \int_0^{\tau_0} d\tau \int_0^{M_1\tau} \frac{d\xi}{[(l_1 - \tau)^2 - (x - \xi)^2 - y^2]^{1/2}} \\ - \frac{\delta_0}{\pi(\lambda + 2\mu)} \int_0^{\tau_1} d\tau \int_{\xi_1}^{M_1\tau} \frac{d\xi}{[(l_1 - \tau)^2 - (x - \xi)^2 - y^2]^{1/2}} \quad \dots(13)$$

where

$$\xi_1 = x - [(l_1 - \tau)^2 - y^2]^{1/2}$$

$\tau_0 =$  may be obtained by solving the set of equations of hyperbolic (7) and the straight line  $\xi = 0$  i.e.,

$$\tau_0 = l_1 - [x^2 - y^2]^{1/2} \quad \dots(14)$$

$\tau_1 =$  may be obtained by solving the set of equations of hyperbolic (7) and the two straight lines

$$\xi = \pm M_1\tau \text{ i.e.,}$$

$$\tau_1 = \frac{1}{1 - M_1^2} [-(M_1x - l_1) \\ \pm \{(M_1x - l_1)^2 - (1 - M_1^2)(l_1^2 - x^2 - y^2)\}^{1/2}] \quad \dots(15)$$

By differentiating eqn. (13) with respect to  $x$  and  $y$  we get

$$\frac{\partial W}{\partial y} = \frac{\delta_0}{(\lambda + 2\mu)} \left( \sin^{-1} \frac{x}{[(l_1 - \tau_0)^2 - y^2]^{1/2}} \right) \frac{\partial \tau_0}{\partial y} \\ - \frac{\delta_0}{(\lambda + 2\mu)} \left( \sin^{-1} \frac{x}{\{(l_1 - \tau_1)^2 - y^2\}^{1/2}} \right) \frac{\partial \tau_1}{\partial y} +$$

(equation continued on p. 1263)

$$\begin{aligned}
 & + \frac{\delta_0}{(\lambda + 2)} (x - M_1 l_1 - M_1 y) \int_0^{l_1 - \tau_1} \frac{dz}{(z + y) \sqrt{R_1}} \\
 & + \frac{\delta_0}{(\lambda + 2\mu)} \int_{l_1}^{l_1 - \tau_1} \frac{dz}{(z - y) \sqrt{R_1}} \quad \dots(16)
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial W}{\partial x} & = \frac{\delta_0}{(\lambda + 2\mu)} \left( \sin^{-1} \frac{x}{[(l_1 - \tau_0)^2 - y^2]^{1/2}} \right) \frac{\partial \tau_0}{\partial x} \\
 & - \frac{\delta_0}{(\lambda + 2\mu)} \left( \sin^{-1} \frac{x}{[(l_1 - \tau_1) - y^2]^{1/2}} \right) \frac{\partial \tau_1}{\partial x} \\
 & - \frac{\delta_0}{(\lambda + 2\mu)} \int_{l_1}^{l_1 - \tau_1} \frac{dz}{\sqrt{R_1}} - \frac{\delta_0}{(\lambda + 2\mu)} \int_{l_1}^{l_1 - \tau_1} \frac{dz}{[(z^2 - x^2 - y^2)]^{1/2}} \quad \dots(17)
 \end{aligned}$$

where

$$R_1 = (1 - M_1^2) z^2 + 2M_1(x - M_1 l_1) z - Y^2 - (x - M_1 l_1)^2.$$

From (11) we have

$$C_2 = \frac{1}{\pi} \left( \frac{\partial W}{\partial x} \right)_{y=0} \quad \dots(18)$$

Accordingly from (6) an expression for  $V(x, y, t)$  may be obtained in the form

$$\begin{aligned}
 V & = \frac{1}{\pi} \int_0^{\bar{\tau}_0} d\tau \int_0^{M_1 \tau} \frac{\left( \frac{\partial W}{\partial x} \right)_{y=0} d\xi}{\{(l_2 - \tau)^2 - (x - \xi)^2 - y^2\}^{1/2}} \\
 & - \frac{1}{\pi} \int_0^{\bar{\tau}_1} d\tau \int_{\xi_1}^{M_2 \tau} \frac{\left( \frac{\partial W}{\partial x} \right)_{y=0} d\xi}{\{(l_2 - \tau)^2 - (x - \xi)^2 - y^2\}^{1/2}} \quad \dots(19)
 \end{aligned}$$

where  $\bar{\tau}_0, \bar{\tau}_1$  and  $\bar{\xi}_1$  can be obtained by replacing  $l_1$  and  $M_1$  by  $l_2$  and  $M_2$  in the expressions given for  $\tau_0, \tau_1$  and  $\xi_1$ .

By differentiating eqn. (19) with respect to  $x$  and  $y$  we get

$$\begin{aligned}
 \frac{\partial V}{\partial x} & = \frac{1}{\pi} \left( \frac{\partial W}{\partial x} \right)_{y=0} \left( \sin^{-1} \frac{x}{\{(l_2 - \bar{\tau}_0)^2 - y^2\}^{1/2}} \right) \frac{\partial \bar{\tau}_0}{\partial x} \\
 & - \frac{1}{\pi} \left( \frac{\partial W}{\partial x} \right)_{y=0} \left( \sin^{-1} \frac{x}{\{(l_2 - \bar{\tau}_1) - y^2\}^{1/2}} \right) \frac{1}{x} +
 \end{aligned}$$

*(equation continued on p. 1264)*

$$\begin{aligned}
& + \frac{1}{\pi} \frac{\partial}{\partial x} \left( \frac{\partial W}{\partial x} \right)_{y=0} \int_0^{\bar{\tau}_0} \sin^{-1} \frac{x - M_2 \tau}{\{(l_2 - \tau)^2 - y^2\}^{1/2}} d\tau \\
& - \frac{1}{\pi} \frac{\partial}{\partial x} \left( \frac{\partial W}{\partial x} \right)_{y=0} \int_0^{\bar{\tau}_0} \sin^{-1} \frac{x}{\{(l_2 - \tau)^2 - y^2\}^{1/2}} d\tau \\
& + \frac{1}{\pi} \left( \frac{\partial W}{\partial x} \right)_{y=0} \int_{l_2}^{l_2 - \bar{\tau}_1} \frac{dz}{\sqrt{R_1}} + \frac{1}{\pi} \left( \frac{\partial W}{\partial x} \right)_{y=0} \\
& \quad \times \int_{l_2}^{l_2 - \bar{\tau}_1} \frac{dz}{\{z^2 - x^2 - y^2\}^{1/2}} \quad \dots(20)
\end{aligned}$$

$$\begin{aligned}
\frac{\partial V}{\partial y} &= \frac{1}{\pi} \left( \frac{\partial W}{\partial x} \right)_{y=0} \sin^{-1} \frac{x}{[(l_2 - \tau_0)^2 - y^2]^{1/2}} \frac{\partial \bar{\tau}_0}{\partial y} \\
& - \frac{1}{\pi} \left( \frac{\partial W}{\partial y} \right)_{y=0} \sin^{-1} \frac{x}{[(l_2 - \tau_1)^2 - y^2]^{1/2}} \frac{\partial \bar{\tau}_1}{\partial y} \\
& + \frac{1}{\pi} \left( \frac{\partial W}{\partial x} \right)_{y=0} (x - M_2 l_2 - M_2 y) \int_{l_2}^{l_2 - \bar{\tau}_1} \frac{dz}{(z + y) [R_1]^{1/2}} \\
& + \frac{1}{\pi} \left( \frac{\partial W}{\partial x} \right)_{y=0} \int_{l_2}^{l_2 - \bar{\tau}_1} \frac{dz}{(z^2 - x^2 - y^2)^{1/2}} \quad \dots(21)
\end{aligned}$$

Knowing the components of strains it is easy to find the stresses by use of Hook's law. Putting the value of  $C_2$  in (10) we can find  $C_1$  in the second approximation, then we have:

$$C_1(x, l) = \frac{\delta_0 - \left( \frac{\partial V}{\partial x} \right)_{y=0}}{\pi(\lambda + 2\mu)} = f_1(x, l) \quad \dots(22)$$

From (22) and (5) we can get  $W$  in the second approximation

$$\begin{aligned}
W &= \frac{f_1(x, l)}{\pi(\lambda + 2\mu)} \int_0^{\tau_0} d\tau \int_0^{M_1 \tau} \frac{M_1 d\xi}{[(l_1 - \tau)^2 - (x - \xi)^2 - y^2]^{1/2}} \\
& - \frac{f_1(x, l)}{\pi(\lambda + 2\mu)} \int_0^{\tau_0} d\tau \int_{\xi_1}^{M_1 \tau} \frac{d\xi}{[(l_1 - \tau)^2 - (x - \xi)^2 - y^2]^{1/2}}
\end{aligned}$$

The second approximation of  $C_2$  can now be obtained for eqn. (11) by substituting for  $C_1$  from eqn. (22) i.e.

$$C_2 = - \frac{1}{\lambda + 2\mu} \frac{\partial}{\partial x} \iint_{\delta_2} \frac{\delta_0 - \left( \frac{\partial W}{\partial x} \right)_{v=0} d\xi d\tau}{[(l_2 - \tau)^2 - (x - \xi)^2 - y^2]^{1/2}} = f_2(x, l_2).$$

By putting the function  $f_2(x, l_2)$  instead of the term  $\left( \frac{\partial W}{\partial x} \right)_{v=0}$  in eqns. (19), (20) and (21) we obtain similar expressions for  $V$ ,  $\frac{\partial V}{\partial x}$  and  $\frac{\partial V}{\partial y}$ .

The results for  $y = 0.5$  and for different values of  $x$  are shown in Figs. 2-5.

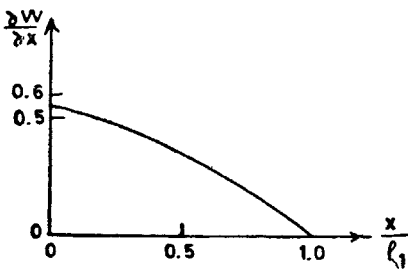


FIG. 2.

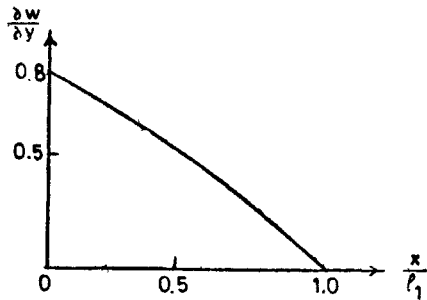


FIG. 3.

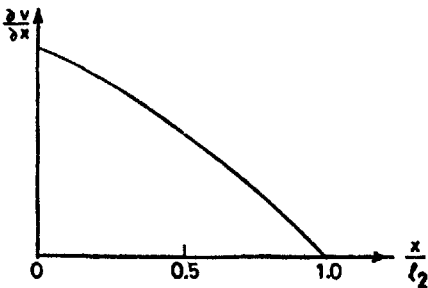


FIG. 4.

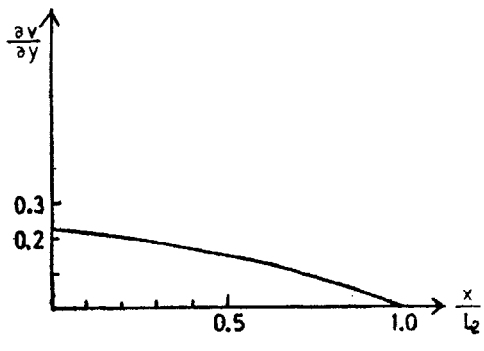


FIG. 5.

REFERENCE

El-Dewik, Fawze Shaban (1975). On the propagation of elastic waves in the half-plane. *Spornik Asperantor Mokh. Institute*, N. 2. (In Russian).