

# GENERALIZED INFORMATION-IMPROVEMENT FUNCTIONS

by RAM AUTAR\*, *Faculty of Mathematics, University of Delhi, Delhi 7*

(Communicated by F. C. Auluck, F.N.A.)

(Received 30 March 1973)

Theil (1967) has studied 'information-improvement' which has found applications in economics. A characterization of Theil's measure has been studied by Sharma and Autar (1973). In this paper a generalized measure of 'information-improvement' through a functional equation has been obtained.

## 1. INTRODUCTION

Let  $P = (p_1, \dots, p_n)$  be the posterior probability distribution of a set of  $n$  events on the basis of an experiment  $E$  whose a priori distribution (prediction) is  $Q = (q_1, \dots, q_n)$ , then

$$I(P; Q) = \sum_{i=1}^n p_i \log_2 (p_i/q_i), p_i, q_i \geq 0, \sum_{i=1}^n p_i = \sum_{i=1}^n q_i = 1 \quad \dots(1.1)$$

is Kullback's (1959) expected information from this experiment. Theil (1967) has given two important interpretations of this measure : one as the information content of the prediction and other as information inaccuracy of the prediction. Continuing the second interpretation Theil defines 'information-improvement measure'

$$T(P; Q; R) = \sum_{i=1}^n p_i \log_2 (r_i/q_i) \quad \dots(1.2)$$

where  $R = (r_1, \dots, r_n)$ ,  $r_i \geq 0$ ,  $\sum_{i=1}^n r_i = 1$  is the revised prediction probability distribution of the original prediction  $Q = (q_1, \dots, q_n)$  on the basis of the distribution  $P = (p_1, \dots, p_n)$  obtained from the experiment  $E$ .

A systematic study through functional equation which arises by considering certain postulates of this measure is made in a paper (for entropy refer Daroczy 1970) by Sharma and Autar (1973) defining the information-improvement function as follows :

---

\*Present address : Department of Education in Science and Mathematics, NCERT, Sri Aurobindo Marg, New Delhi 110016.

A function  $f(x; y; z)$  satisfying the functional equation

$$\begin{aligned} f(x_1; y_1; z_1) + (1 - x_1)f\left(\frac{x_2}{1 - x_1}; \frac{y_2}{1 - y_1}; \frac{z_2}{1 - z_1}\right) \\ = f(x_2; y_2; z_2) + (1 - x_2)f\left(\frac{x_1}{1 - x_2}; \frac{y_1}{1 - y_2}; \frac{z_1}{1 - z_2}\right) \end{aligned} \quad \dots(1.3)$$

for all  $(x_1, x_2), (y_1, y_2)$  and  $(z_1, z_2) \in D$  where

$$D = \{(t_1, t_2) : t_1, t_2 \in [0, 1), t_1 + t_2 \leq 1\} \quad \dots(1.4)$$

and the boundary conditions

$$f(0; 0; 0) = f(1; 1; 1); f(1; \frac{1}{2}; 1) = 1 \quad \dots(1.5)$$

is called information-improvement function which under some additional conditions like continuity etc. leads to Theil's information-improvement function

$$f_T(x; y; z) = x \log_2(z/y) + (1 - x) \log_2\{(1 - z)(1 - y)^{-1}\} \quad \dots(1.6)$$

if  $x, y, z \in [0, 1]$  excluding those points of the region where function becomes  $\pm \infty$ .

(We assume  $0 \log 0 = 0 \log \frac{0}{0} = 0$ ).

In this paper we have generalized (1.3) for two parameters viz.  $\alpha, \beta > 0$ . A characterization of the corresponding generalized information-improvement function and measure is given. Some of the properties of the generalized measure have also been incorporated.

## 2. INFORMATION-IMPROVEMENT FUNCTION OF TYPE $(\alpha, \beta)$ AND A CHARACTERIZATION THEOREM

We generalize (1.3) by introducing two parameters as

$$\begin{aligned} f(x_1; y_1; z_1) + (1 - x_1)^\alpha (1 - y_1)^{\alpha - \beta} (1 - z_1)^{\beta - \alpha} f\left(\frac{x_2}{1 - x_1}; \frac{y_2}{1 - y_1}; \frac{z_2}{1 - z_1}\right) \\ = f(x_2; y_2; z_2) + (1 - x_2)^\alpha (1 - y_2)^{\alpha - \beta} (1 - z_2)^{\beta - \alpha} \\ \times f\left(\frac{x_1}{1 - x_2}; \frac{y_1}{1 - y_2}; \frac{z_1}{1 - z_2}\right) \end{aligned} \quad \dots(2.1)$$

$\alpha, \beta > 0$  with  $\beta \neq \alpha$ .

**Definition 1** — A real function  $f: K \rightarrow R$  where  $K = [0, 1] \times [0, 1] \times [0, 1]$  and  $R$ , set of reals, is called information-improvement function of type  $(\alpha, \beta)$  if  $f$  satisfies (2.1) and (1.5).

Now we characterize information-improvement function of type  $(\alpha, \beta)$ .

*Theorem 1* — If  $f(x; y; z)$  satisfies the functional equation (2.1) and the boundary conditions (1.5) then for all  $x, y, z \in [0, 1]$

$$f(x; y; z) = f_T^{(\alpha, \beta)}(x; y; z)$$

where

$$f_T^{(\alpha, \beta)}(x; y; z) = (2^{\beta-\alpha} - 1)^{-1} [x^\alpha y^{\alpha-\beta} z^{\beta-\alpha} + (1-x)^\alpha (1-y)^{\alpha-\beta} (1-z)^{\beta-\alpha} - 1] \quad \dots(2.2)$$

for  $\alpha, \beta > 0$  with  $\beta \neq \alpha$ .

PROOF: By putting  $x_1 = y_1 = z_1 = 0$  in (2.1) and using (1.5) we get

$$f(0; 0; 0) = f(1; 1; 1) = 0. \quad \dots(2.3)$$

Taking  $x_2 = 1 - x_1, y_2 = 1 - y_1$  and  $z_2 = 1 - z_1$  in (2.1) and utilizing (2.3) we have

$$f(x_1; y_1; z_1) = f(1 - x_1; 1 - y_1; 1 - z_1), \text{ for all } x_1, y_1, z_1 \in [0, 1]. \quad \dots(2.4)$$

Next setting  $p_1 = 1 - x_1, q_1 = 1 - y_1, r_1 = 1 - z_1, p_2 = x_2(1 - x_1)^{-1}, q_2 = y_2(1 - y_1)^{-1}$  and  $r_2 = z_2(1 - z_1)^{-1}$  in (2.1) and using (2.4), we get

$$\begin{aligned} f(p_1; q_1; r_1) + p_1^\alpha q_1^{\alpha-\beta} r_1^{\beta-\alpha} f(p_2; q_2; r_2) \\ = f(p_1 p_2; q_1 q_2; r_1 r_2) + (1 - p_1 p_2)^\alpha (1 - q_1 q_2)^{\alpha-\beta} (1 - r_1 r_2)^{\beta-\alpha} \\ \times f\left(\frac{1 - p_1}{1 - p_1 p_2}; \frac{1 - q_1}{1 - q_1 q_2}; \frac{1 - r_1}{1 - r_1 r_2}\right). \quad \dots(2.5) \end{aligned}$$

Consider now for arbitrary  $p_1, q_1, r_1 \in (0, 1], p_2, q_2, r_2 \in [0, 1]$  the function  $F$  defined by

$$\begin{aligned} F(p_1, p_2; q_1, q_2; r_1, r_2) = f(p_1; q_1; r_1) \\ + \left[ p_1^\alpha q_1^{\alpha-\beta} r_1^{\beta-\alpha} + (1 - p_1)^\alpha (1 - q_1)^{\alpha-\beta} (1 - r_1)^{\beta-\alpha} \right] f(p_2; q_2; r_2). \quad \dots(2.6) \end{aligned}$$

We prove that  $F$  defined above is symmetric, i.e.

$$F(p_1, p_2; q_1, q_2; r_1, r_2) = F(p_2, p_1; q_2, q_1; r_2, r_1). \quad \dots(2.7)$$

Now (2.6) with (2.5) gives

$$\begin{aligned} F(p_1, p_2; q_1, q_2; r_1, r_2) \\ = f(p_1 p_2; q_1 q_2; r_1 r_2) + (1 - p_1 p_2)^\alpha (1 - q_1 q_2)^{\alpha-\beta} (1 - r_1 r_2)^{\beta-\alpha} \\ \times \left[ f\left(\frac{1 - p_1}{1 - p_1 p_2}; \frac{1 - q_1}{1 - q_1 q_2}; \frac{1 - r_1}{1 - r_1 r_2}\right) + \left(\frac{1 - p_1}{1 - p_1 p_2}\right)^\alpha \right. \\ \left. \times \left(\frac{1 - q_1}{1 - q_1 q_2}\right)^{\alpha-\beta} \left(\frac{1 - r_1}{1 - r_1 r_2}\right)^{\beta-\alpha} f(p_2; q_2; r_2) \right]. \quad \dots(2.8) \end{aligned}$$

If we set  $p_1^* = (1 - p_1)(1 - p_1 p_2)^{-1}$ ,  $q_1^* = (1 - q_1)(1 - q_1 q_2)^{-1}$  and  $r_1^* = (1 - r_1)(1 - r_1 r_2)^{-1}$ , then from (2.4) and (2.5) it can be easily verified that

$$\begin{aligned} G(p_1, p_2; q_1, q_2; r_1, r_2) &= f\left(\frac{1 - p_1}{1 - p_1 p_2}; \frac{1 - q_1}{1 - q_1 q_2}; \frac{1 - r_1}{1 - r_1 r_2}\right) \\ &\quad + \left(\frac{1 - p_1}{1 - p_1 p_2}\right)^\alpha \left(\frac{1 - q_1}{1 - q_1 q_2}\right)^{\alpha - \beta} \left(\frac{1 - r_1}{1 - r_1 r_2}\right)^{\beta - \alpha} f(p_2; q_2; r_2) \\ &= f\left(\frac{1 - p_2}{1 - p_1 p_2}; \frac{1 - q_2}{1 - q_1 q_2}; \frac{1 - r_2}{1 - r_1 r_2}\right) \\ &\quad + \left(\frac{1 - p_2}{1 - p_1 p_2}\right)^\alpha \left(\frac{1 - q_2}{1 - q_1 q_2}\right)^{\alpha - \beta} \left(\frac{1 - r_2}{1 - r_1 r_2}\right)^{\beta - \alpha} f(p_1; q_1; r_1) \\ &= G(p_2, p_1; q_2, q_1; r_2, r_1). \end{aligned}$$

This proves (2.7). Now putting  $p_2 = r_2 = 0$ ,  $q_2 = \frac{1}{2}$  in (2.7) then from (2.6), (2.4) and  $f(1; \frac{1}{2}; 1) = 1$  we get

$$\begin{aligned} f(p_1; q_1; r_1) &= (2^{\beta - \alpha} - 1)^{-1} \left[ p_1^\alpha q_1^{\alpha - \beta} r_1^{\beta - \alpha} + (1 - p_1)^\alpha (1 - q_1)^{\alpha - \beta} \right. \\ &\quad \left. \times (1 - r_1)^{\beta - \alpha} - 1 \right] \end{aligned}$$

for all  $p_1; q_1; r_1 \in (0, 1]$ ,  $\beta \neq \alpha$ . This formula is true in the cases  $p_1 = q_1 = r_1 = 0$  or  $p_1 = q_1 = r_1 = 1$  by the boundary conditions (1.5). Also (2.7) with (2.6), (2.4) and the above relation, we can easily determine the values of  $f(1; 1; 0)$ ,  $f(0; 0; 1)$ ,  $f(1; 0; 0)$ ,  $f(0; 1; 1)$ ,  $f(1; 0; 1)$ ,  $f(0; 1; 0)$  and  $f(1; q_2; 0)$ ,  $f(1; 0; r_2)$ ,  $f(p_2; 0; 1) \in [0, 1)$  etc. and value of each is  $(1 - 2^{\beta - \alpha})^{-1}$ . This completes the proof of the theorem.

*Note*: It is to be noted that for  $\alpha = 1$ ,  $\beta \rightarrow 1$ , (2.2) reduces to Theil's information-improvement function (1.6).

*Definition 2* — Let  $P = (p_1, \dots, p_n)$ ,  $Q = (q_1, \dots, q_n)$  and  $R = (r_1, \dots, r_n)$  be three probability distributions belonging to  $\Delta_n = \{(p_1, \dots, p_n) : p_i \geq 0 \sum_{i=1}^n p_i = 1\}$ .

We define  $I_n^{(\alpha, \beta)}(P; Q; R)$ , the information-improvement of type  $(\alpha, \beta)$  as

$$I_n^{(\alpha, \beta)}(P; Q; R) = \sum_{i=2}^n s_i^\alpha t_i^{\alpha - \beta} u_i^{\beta - \alpha} f\left(\frac{p_i}{s_i}; \frac{q_i}{t_i}; \frac{r_i}{u_i}\right) \quad \dots(2.9)$$

where  $s_i = p_1 + \dots + p_i$ ,  $t_i = q_1 + \dots + q_i$ ,  $u_i = r_1 + \dots + r_i$  ( $i = 2, 3, \dots, n$ ) and  $f$  is an information-improvement function of type  $(\alpha, \beta)$ . Now, in view of (2.2), (2.9) reduces to

$$I_n^{(\alpha, \beta)}(P; Q; R) = (2^{\beta-\alpha} - 1)^{-1} \left( \sum_{i=1}^n p_i^\alpha q_i^{\alpha-\beta} r_i^{\beta-\alpha} - 1 \right), \beta \neq \alpha. \dots(2.10)$$

Note :  $I_n^{(\alpha, \beta)}(P; Q; R)$  in (2.10) is a generalization of Theil's information-improvement as for  $\alpha = 1$  and  $\beta \rightarrow 1$ , (2.10) reduces to (1.2).

### 3. PROPERTIES AND CHARACTERIZATION OF $I_n^{(\alpha, \beta)}(P; Q; R)$

This section deals with some properties and a characterization of  $I_n^{(\alpha, \beta)}(P; Q; R)$ .

It is the characterization contained in Theorem 5 that places the new measure on a sound mathematical basis and the properties discussed make it amenable for further study and applications. The characterization has been done on the basis of certain simple postulates. As regards some of the properties contained in various theorems, Theorem 2 establishes a relation between two sets of measures to the measure associated with the direct product of their distributions. This is a property which is basic and brings out the non-additive character of the measure studied in this paper. If  $\alpha = 1$ ,  $\beta \rightarrow 1$ , the additive property tallies with that of Theil's measure. Theorem 3 deals with a kind of grouping property and Theorem 4 with what may be called as convexity of the measure. It may be pointed out that such properties are useful while optimizing a given measure which may be an area for future study of this measure.

Several properties like symmetry, expansibility i.e.

$$I_n^{(\alpha, \beta)} \left( \begin{matrix} p_1, \dots, p_n, 0; \\ q_1, \dots, q_n, 0; \\ r_1, \dots, r_n, 0 \end{matrix} \right) = I_n^{(\alpha, \beta)} \left( \begin{matrix} p_1, \dots, p_n; \\ q_1, \dots, q_n; \\ r_1, \dots, r_n \end{matrix} \right)$$

and normalization ( $I_2^{(\alpha, \beta)}(1, 0; \frac{1}{2}; \frac{1}{2}; 1, 0) = 1$ ) etc. (refer Aczél 1969) can be easily derived for  $I_n^{(\alpha, \beta)}(P; Q; R)$ . We state now some other properties.

(i) *Strongly Additive Type* ( $\alpha, \beta$ )

$$I_{mn}^{(\alpha, \beta)} \left( \begin{matrix} p_1 p_{11}, p_1 p_{12}, \dots, p_1 p_{1n}, \dots, p_m p_{m1}, p_m p_{m2}, \dots, p_m p_{mn}; \\ q_1 q_{11}, q_1 q_{12}, \dots, q_1 q_{1n}, \dots, q_m q_{m1}, q_m q_{m2}, \dots, q_m q_{mn} \\ r_1 r_{11}, r_1 r_{12}, \dots, r_1 r_{1n}, \dots, r_m r_{m1}, r_m r_{m2}, \dots, r_m r_{mn} \end{matrix} \right) =$$

(equation contd. p. 558)

$$= I_m^{(\alpha, \beta)} \begin{pmatrix} p_1, \dots, p_m; \\ q_1, \dots, q_m; \\ r_1, \dots, r_m \end{pmatrix} + \sum_{j=1}^m p_j^\alpha q_j^{\alpha-\beta} r_j^{\beta-\alpha} I_n^{(\alpha, \beta)} \begin{pmatrix} p_{j_1}, \dots, p_{j_n}; \\ q_{j_1}, \dots, q_{j_n}; \\ r_{j_1}, \dots, r_{j_n} \end{pmatrix}$$

where  $\sum_{k=1}^n p_{ik} = \sum_{k=1}^n q_{ik} = \sum_{k=1}^n r_{ik} = 1$  for all  $j = 1, 2, \dots, m$ .

(ii) *Recursive Type*  $(\alpha, \beta)$

$$I_n^{(\alpha, \beta)} \begin{pmatrix} p_1, p_2, \dots, p_n; \\ q_1, q_2, \dots, q_n; \\ r_1, r_2, \dots, r_n \end{pmatrix} - I_{n-1}^{(\alpha, \beta)} \begin{pmatrix} p_1 + p_2, p_3, \dots, p_n; \\ q_1 + q_2, q_3, \dots, q_n; \\ r_1 + r_2, r_3, \dots, r_n \end{pmatrix}$$

$$= (p_1 + p_2)^\alpha (q_1 + q_2)^{\alpha-\beta} (r_1 + r_2)^{\beta-\alpha} I_2^{(\alpha, \beta)} \begin{pmatrix} p_1/(p_1 + p_2), p_2/(p_1 + p_2); \\ q_1/(q_1 + q_2), q_2/(q_1 + q_2); \\ r_1/(r_1 + r_2), r_2/(r_1 + r_2) \end{pmatrix}$$

for all  $(p_1, \dots, p_n)$ , and  $(q_1, \dots, q_n)$  and  $(r_1, \dots, r_n) \in \Delta_n$ .

An interesting special case of (1) above is given in the next theorem.

**Theorem 2** — Let  $P_1 = (p_{11}, p_{12}, \dots, p_{1n}) \in \Delta_n$ ,  $P_2 = (p_{21}, p_{22}, \dots, p_{2m}) \in \Delta_m$  and similar notations for  $Q_1, Q_2$  and  $R_1, R_2$ . Define

$$P_1 * P_2 = (p_{11} p_{21}, \dots, p_{11} p_{2m}, \dots, p_{1n} p_{21}, \dots, p_{1n} p_{2m}) \quad \dots(3.1)$$

then we have

$$I_{mn}^{(\alpha, \beta)} (P_1 * P_2; Q_1 * Q_2; R_1 * R_2) = I_n^{(\alpha, \beta)} (P_1; Q_1; R_1) + I_m^{(\alpha, \beta)} (P_2; Q_2; R_2)$$

$$+ (2^{\beta-\alpha} - 1) I_n^{(\alpha, \beta)} (P_1; Q_1; R_1) I_m^{(\alpha, \beta)} (P_2; Q_2; R_2) \quad \dots(3.2)$$

for  $\alpha, \beta > 0$  ( $\beta \neq \alpha$ ).

**PROOF:** We have

$$I_{mn}^{(\alpha, \beta)} (P_1 * P_2; Q_1 * Q_2; R_1 * R_2)$$

$$= (2^{\beta-\alpha} - 1)^{-1} \left[ \sum_{i=1}^n \sum_{j=1}^m (p_{1i} p_{2j})^\alpha (q_{1i} q_{2j})^{\alpha-\beta} (r_{1i} r_{2j})^{\beta-\alpha} - 1 \right]$$

$$= (2^{\beta-\alpha} - 1)^{-1} \left[ \sum_{i=1}^n \left( p_{1i}^\alpha q_{1i}^{\alpha-\beta} r_{1i}^{\beta-\alpha} \right) \sum_{j=1}^m \left( p_{2j}^\alpha q_{2j}^{\alpha-\beta} r_{2j}^{\beta-\alpha} \right) - 1 \right]$$

$$\begin{aligned}
 &= (2^{\beta-\alpha} - 1)^{-1} \left[ \left\{ (2^{\beta-\alpha} - 1) I_n^{(\alpha, \beta)}(P_1; Q_1; R_1) + 1 \right\} \right. \\
 &\quad \left. \times \left\{ (2^{\beta-\alpha} - 1) I_m^{(\alpha, \beta)}(P_2; Q_2; R_2) + 1 \right\} - 1 \right] \\
 &= I_n^{(\alpha, \beta)}(P_1; Q_1; R_1) + I_m^{(\alpha, \beta)}(P_2; Q_2; R_2) \\
 &\quad + (2^{\beta-\alpha} - 1) I_n^{(\alpha, \beta)}(P_1; Q_1; R_1) I_m^{(\alpha, \beta)}(P_2; Q_2; R_2).
 \end{aligned}$$

When  $\beta \rightarrow 1$  and  $\alpha = 1$  the last term in (3.2) vanishes and we have

$$\begin{aligned}
 I_{mn}^{(\alpha, \beta)}(P_1 * P_2; Q_1 * Q_2; R_1 * R_2) &= I_n^{(\alpha, \beta)}(P_1; Q_1; R_1) \\
 &\quad + I_m^{(\alpha, \beta)}(P_2; Q_2; R_2).
 \end{aligned}$$

Also for  $\beta \neq \alpha$  we have

$$\begin{aligned}
 I_{mn}^{(\alpha, \beta)}(P_1 * P_2; Q_1 * Q_2; R_1 * R_2) &\geq I_n^{(\alpha, \beta)}(P_1; Q_1; R_1) \\
 &\quad + I_m^{(\alpha, \beta)}(P_2; Q_2; R_2)
 \end{aligned}$$

according as

$$(2^{\beta-\alpha} - 1) I_n^{(\alpha, \beta)}(P_1; Q_1; R_1) I_m^{(\alpha, \beta)}(P_2; Q_2; R_2) \geq 0.$$

The following theorem is a generalization of recursivity of  $I_n^{(\alpha, \beta)}$ .

*Theorem 3* — Let  $\alpha, \beta$  be the positive numbers such that  $\beta \neq \alpha$ . For  $n \geq k + 1$  where  $k \geq 2$ ,

$$\begin{aligned}
 &I_n^{(\alpha, \beta)} \left( \begin{matrix} p_1, \dots, p_n; \\ q_1, \dots, q_n; \\ r_1, \dots, r_n \end{matrix} \right) - I_{n-k+1}^{(\alpha, \beta)} \left( \begin{matrix} \sum p_i, p_{k+1}, \dots, p_n; \\ \sum q_i, q_{k+1}, \dots, q_n; \\ \sum r_i, r_{k+1}, \dots, r_n \end{matrix} \right) \\
 &= (\sum p_i)^\alpha (\sum q_i)^{\alpha-\beta} (\sum r_i)^{\beta-\alpha} I_k^{(\alpha, \beta)} \left( \begin{matrix} p_1/\sum p_i, \dots, p_k/\sum p_i; \\ q_1/\sum q_i, \dots, q_k/\sum q_i; \\ r_1/\sum r_i, \dots, r_k/\sum r_i \end{matrix} \right) \dots(3.3)
 \end{aligned}$$

for all  $(p_1, \dots, p_n), (q_1, \dots, q_n)$  and  $(r_1, \dots, r_n) \in \Delta_n$  and  $\Sigma$  stands for  $\sum_{i=1}^k$  unless otherwise specified.

PROOF : Left-hand expression of (3.3) can be written as

$$\begin{aligned}
 & (2^{\beta-\alpha} - 1)^{-1} \left[ \left( \sum_{i=1}^n p_i^\alpha q_i^{\alpha-\beta} r_i^{\beta-\alpha} - 1 \right) - \left\{ (\sum p_i)^\alpha (\sum q_i)^{\alpha-\beta} (\sum r_i)^{\beta-\alpha} \right. \right. \\
 & \qquad \qquad \qquad \left. \left. + \sum_{j=k+1}^n p_j^\alpha q_j^{\alpha-\beta} r_j^{\beta-\alpha} - 1 \right\} \right] \\
 & = (\sum p_i)^\alpha (\sum q_i)^{\alpha-\beta} (\sum r_i)^{\beta-\alpha} (2^{\beta-\alpha} - 1)^{-1} \\
 & \qquad \qquad \qquad \times \left[ \sum_{j=1}^k (p_j/\sum p_i)^\alpha (q_j/\sum q_i)^{\alpha-\beta} (r_j/\sum r_i)^{\beta-\alpha} - 1 \right] \\
 & = (\sum p_i)^\alpha (\sum q_i)^{\alpha-\beta} (\sum r_i)^{\beta-\alpha} I_k^{(\alpha, \beta)} \left( \begin{array}{c} p_1/\sum p_i, \dots, p_k/\sum p_i; \\ q_1/\sum q_i, \dots, q_k/\sum q_i; \\ r_1/\sum r_i, \dots, r_k/\sum r_i \end{array} \right).
 \end{aligned}$$

It is an open problem as to for what values of  $\alpha$  and  $\beta$ ,  $I_n^{(\alpha, \beta)} > 0$ . Considering the possibility of these being positive we may prove the following theorem.

*Theorem 4* — For  $(p_1, \dots, p_n) \in \Delta_n$ ,  $(q_1, \dots, q_m)$ ,  $(r_1, \dots, r_m)$  and  $(q_{1i}, \dots, q_{mi}) \in \Delta_m$  ( $i = 1, \dots, n$ ) we have

$$I_m^{(\alpha, \beta)} \left( \begin{array}{c} \sum_{i=1}^n p_i q_{1i}, \dots, \sum_{i=1}^n p_i q_{mi}; \\ q_1, \dots, q_m; \\ r_1, \dots, r_m \end{array} \right) \geq \sum_{i=1}^n p_i I_m^{(\alpha, \beta)} \left( \begin{array}{c} q_{1i}, \dots, q_{mi}; \\ q_1, \dots, q_m; \\ r_1, \dots, r_m \end{array} \right) \quad \dots(3.4)$$

where  $0 < \alpha < 1$ ,  $\beta > 0$ . The inequality is reversed if  $1 < \alpha < \infty$ .

PROOF : We have

$$I_m^{(\alpha, \beta)} \left( \begin{array}{c} \sum_{i=1}^n p_i q_{1i}, \dots, \sum_{i=1}^n p_i q_{mi}; \\ q_1, \dots, q_m; \\ r_1, \dots, r_m \end{array} \right) = (2^{\beta-\alpha} - 1)^{-1} \left[ \sum_{k=1}^m \left( \sum_{i=1}^n p_i q_{ki} \right)^\alpha \right. \\
 \qquad \qquad \qquad \left. q_k^{\alpha-\beta} r_k^{\beta-\alpha} - 1 \right]$$



$$\geq (2^{\beta-\alpha} - 1)^{-1} \left( \sum_{k=1}^m \sum_{i=1}^n p_i q_{ki}^\alpha q_k^{\alpha-\beta} r_k^{\beta-\alpha} - 1 \right)$$

if  $\alpha < 1$  (Gallager 1968)

$$= \sum_{i=1}^n p_i I_m^{(\alpha, \beta)} \begin{pmatrix} q_{1i}, \dots, q_{mi}; \\ q_1, \dots, q_m; \\ r_1, \dots, r_m \end{pmatrix}$$

Since  $\left( \sum_{i=1}^n p_i q_{ki} \right)^\alpha \leq \sum_{i=1}^n p_i q_{ki}^\alpha$  for  $\alpha > 1$  (Gallager 1968), therefore, inequality

in (3.4) is reversed.

In the next theorem we attempt to characterize  $I_n^{(\alpha, \beta)}(P; Q; R)$  by imposing some conditions over a sequence of functions  $K_n; S_n \rightarrow R, S_n = \Delta_n \times \Delta_n \times \Delta_n$  ( $n = 2, 3, \dots$ ) so that

$$K_n(P; Q; R) = I_n^{(\alpha, \beta)}(P; Q; R) \tag{3.5}$$

for  $\alpha, \beta > 0$  ( $\beta \neq \alpha$ ).

*Theorem 5* — Let  $K_n : S_n \rightarrow R$  ( $n = 2, 3, \dots$ ) be a sequence of mappings satisfying the following postulates :

(I)  $K_3 \begin{pmatrix} p_1, p_2, p_3; \\ q_1, q_2, q_3; \\ r_1, r_2, r_3 \end{pmatrix}$  is symmetric function of its variables

$$\left\{ \begin{matrix} p_i \\ q_i \\ r_i \end{matrix} \right\}, i = 1, 2, 3 (p_1 + p_2 + p_3 = 1 \text{ etc}).$$

(II)  $K_2(1, 0; \frac{1}{2}, \frac{1}{2}; 1, 0) = 1.$

(III)  $K_n \begin{pmatrix} p_1, p_2, \dots, p_n; \\ q_1, q_2, \dots, q_n; \\ r_1, r_2, \dots, r_n \end{pmatrix} = K_{n-1} \begin{pmatrix} p_1 + p_2, p_3, \dots, p_n; \\ q_1 + q_2, q_3, \dots, q_n; \\ r_1 + r_2, r_3, \dots, r_n \end{pmatrix} =$

(equation contd. p. 562)

$$= (p_1 + p_2)^\alpha (q_1 + q_2)^{\alpha-\beta} (r_1 + r_2)^{\beta-\alpha} K_2 \left( \begin{matrix} p_1/(p_1 + p_2), p_2/(p_1 + p_2); \\ q_1/(q_1 + q_2), q_2/(q_1 + q_2); \\ r_1/(r_1 + r_2), r_2/(r_1 + r_2) \end{matrix} \right)$$

for all  $p_i, q_i, r_i \geq 0$  with  $\sum_{i=1}^n p_i = \sum_{i=1}^n q_i = \sum_{i=1}^n r_i = 1$  ( $n = 3, 4, \dots; p_1 + p_2 > 0, q_1 + q_2 > 0$  and  $r_1 + r_2 > 0$ ).

Then the function  $f$  defined by

$$f(x; y; z) = K_2(x, 1 - x; y, 1 - y; z, 1 - z), x, y, z \in [0, 1] \quad \dots(3.6)$$

is an information-improvement function of type  $(\alpha, \beta)$  and that (3.5) holds.

PROOF : For arbitrary  $(x_1, x_2), (y_1, y_2)$  and  $(z_1, z_2) \in D$  we have from postulate I,

$$K_3 \left( \begin{matrix} x_1, 1 - x_2 - x_1, x_2; \\ y_1, 1 - y_2 - y_1, y_2; \\ z_1, 1 - z_2 - z_1, z_2 \end{matrix} \right) = K_3 \left( \begin{matrix} x_2, 1 - x_1 - x_2, x_1; \\ y_2, 1 - y_1 - y_2, y_1; \\ z_2, 1 - z_1 - z_2, z_1 \end{matrix} \right)$$

from which it follows by (III) and (3.6) that

$$\begin{aligned} & f(1 - x_1; 1 - y_1; 1 - z_1) + (1 - x_1)^\alpha (1 - y_1)^{\alpha-\beta} (1 - z_1)^{\beta-\alpha} \\ & \times f\left(\frac{x_2}{1 - x_1}; \frac{y_2}{1 - y_1}; \frac{z_2}{1 - z_1}\right) = f(1 - x_2; 1 - y_2; 1 - z_2) \\ & + (1 - x_2)^\alpha (1 - y_2)^{\alpha-\beta} (1 - z_2)^{\beta-\alpha} f\left(\frac{x_1}{1 - x_2}; \frac{y_1}{1 - y_2}; \frac{z_1}{1 - z_2}\right). \end{aligned} \quad \dots(3.7)$$

Now putting  $x_1 = y_1 = z_1 = 0$  and  $x_2 = y_2 = z_2 = \frac{1}{2}$  in (3.7) we get

$$f(1; 1; 1) = 2^{-\alpha} f(0; 0; 0). \quad \dots(3.8)$$

Again from postulate (I) and (3.6) we have

$$K_3 \left( \begin{matrix} 1, 0, 0; \\ 1, 0, 0; \\ 1, 0, 0 \end{matrix} \right) = K_3 \left( \begin{matrix} 0, 1, 0; \\ 0, 1, 0; \\ 0, 1, 0 \end{matrix} \right)$$

or  $f(1; 1; 1) = f(0; 0; 0). \quad \dots(3.9)$

Combining (3.9) with (3.8) we get

$$f(1; 1; 1) = f(0; 0; 0) = 0. \quad \dots(3.10)$$

Next, from postulates (III) (for  $n = 3$ ), postulate (I) and (3.6) we have

$$f(x_1; y_1; z_1) = f(1 - x_1; 1 - y_1; 1 - z_1) \quad \dots(3.11)$$

for all  $x_1, y_1, z_1 \in [0, 1]$ .

Now (3.7) with (3.11) gives (2.1). Thus  $f$  defined in (3.6) is an information-improvement function of type  $(\alpha, \beta)$ . Further we have from Theorem 1,

$$f(x; y; z) = f_T^{(\alpha, \beta)}(x; y; z).$$

Now result (3.5) follows from the repeated application of postulate (III) using (3.6).

#### ACKNOWLEDGEMENTS

The author is indebted to Dr. Bhu Dev Sharma, University of Delhi, for guidance in carrying out this research work.

He is also grateful to C.S.I.R. (India) for the award of senior research fellowship.

#### REFERENCES

- Aczél, J. (1969). On Different Characterizations of Entropies. Proc. Int. Symp. McMaster University Lecture Notes in Mathematics No. 89. Springer-Verlag, New York, pp. 1-11.
- Aczél, J., and Nath, P. (1972). Axiomatic characterization of some measures of divergence in information. *Z. Wahrs. Verw. Geb.*, **21**, 215-24.
- Daroczy, Z. (1970). Generalized information functions. *Inform. Control*, **16**, 36-51.
- Gallager, R. G. (1968). *Information Theory and Reliable Communication*. John Wiley and Sons, Inc., New York, pp. 522-23.
- Kullback, S. (1959). *Information Theory and Statistics*. John Wiley and Sons, Inc., New York.
- Sharma, B. D., and Ram Autar (1973). Information-improvement functions. *Econometrica*, **42**, 103-12.
- Theil, H. (1967). *Economics and Information Theory*. North-Holland Publ. Co., Amsterdam.