

*Research Paper***Quantitative Detachment Mechanics of *Hydra* from Substrates**NEHA KHETAN, SHAGUN MAHESHWARI¹ and CHAITANYA A ATHALE**Division of Biology, IISER Pune, Dr. Homi Bhabha Road, Pashan, Pune, India*

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Hydra is a fresh water hydrozoan living as a solitary polyp with a sedentary feeder lifestyle attached to a substrate. In times of food shortage they are reported to detach from their substrate and move either by drifting or 'somersaulting'. However, the quantification of the mechanical strength of the adhesion of *Hydra* has not been reported before. Here, we measure the force required to detach *Hydra vulgaris* and *Hydra magnipapillata* from a surface and the role of nutritional state and substrate rigidity. For detachment force measurement, we have developed a calibrated flow system, based on a syringe pump. We find the detachment shear stresses are similar whether the animal is well-fed or starved in the two species tested - *H. vulgaris* and *H. magnipapillata*. On the other hand, adhering to a hard substrate like a glass cover slip requires more force to detach *H. vulgaris* as compared to a soft substrate like polyacrylamide gel. Detachment stresses also differ across the two species in the same state. Taken together, it suggests that mechanics of the substrate and ambient flows in the water body could affect passive locomotion of *Hydra*, while suggesting the magnitude of muscle-based forces required to actively detach it from the substrate.

Keywords: *Hydra*; Laminar Flow Chamber; Drag Force; *H. vulgaris*; *H. magnipapillata*

Introduction

Aquatic life forms, ranging from single-celled to multi-cellular have evolved a variety of strategies to remain static through adhesion to substrates. The specific mechanism by which they achieve this adhesion ranges from suckers and nanometer scale spatulae to biological adhesives (reviewed by Gorb, 2008). Amongst aquatic animals, the adhesion of the mussel *Mytilus edulis* has been particularly well studied (reviewed by Waite 2002). The mussel shells attach to rocky substrates with byssal threads consisting of multiple proteins, each contributing distinct mechanical properties (Lin *et al.*, 2007). The amino acid 3,4-dihydroxy-L-phenylalanine (dopa) is considered a vital component for the mechanical and chemical properties of adhesive, with each molecule of dopa-enriched peptide requiring on an average 805 pN for dissociation from the substrate (Lee *et al.*, 2006).

Hydra on the other hand, are fresh water dwelling Hydrozoans of phylum Cnidaria that live as

solitary polyps, typically found attached to substrates like stems, branches or leaves under-water. Renewed interest in *Hydra* is due to its regenerative ability, along with genome sequence and the evolutionary relatedness of the regenerative pathways to vertebrates (Fujisawa, 2006; Watanabe *et al.*, 2009). In their natural environment, *Hydra* are subjected to gentle flows and so far their movement has been attributed to passive drifting. Wagner has noted that the resistance of an attached *Hydra* to water flows might be an adaptation to the diverse environmental conditions (still and flowing water) that it is exposed to and its inability to actively swim, once suspended in water (Wagner 1905). The movement of *Hydra* that are already attached to a substrate was observed to occur by 'somersaulting'- animals attach their tentacles to a new position, detach the basal disk with body contraction, straighten and reattach the basal disk at a new position near the hypostome (Wagner, 1905). A report on Indian samples of *Hydra vulgaris* described the ability of these animals to actively

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'crawl', a motion that involved 'somersaulting' (Annandale, 1911), similar to that reported earlier. The movement is thought to enable the individual to leave unfavourable environments. The combination of contraction by ectodermal longitudinal muscles and extension by endodermal circular muscles has been used to explain the 'somersaulting' motion. However, a major step in the process necessarily involves the detachment of base. To our knowledge, the mechanics of this detachment is yet to be addressed.

In its sedentary mode, *Hydra* sp. is attached by its basal-body; also called the basal disk or 'foot' to the substrates by a glandular secretion (Brien, 1960). Like other parts of *Hydra*, the animal can also regenerate the basal disk when amputated (Amimoto et al., 2006). Histologically, the cells of the disk consist of an inner endoderm and an outer ectoderm. The cells are glandular, conical in shape and filled with granules (Bode et al., 1986). These cells secrete large amounts of mucus needed for attachment of the animal to substrates. The basal disk was thought for long to be a closed structure but more recently a pore-like structure in the disk called aboral pore (Shimizu et al., 2007) has been found. While the histology of the foot is understood, the nature of mucus as a bioadhesive, which works under water could be interesting, both from a fundamental perspective of adhesives, as well as applications in biocompatible materials (Waite, 2002). Recently, the glue from *Hydra magnipapillata* has been characterised and found to be based on glycans and glycoproteins (Rodrigues et al., 2016a). Additional gene-expression analysis has revealed 21 transcripts to be expressed in the basal disk alone (Rodrigues et al., 2016b). While remaining attached is important for *Hydra*, movement requires the ability to detach and is equally important. However, till date no quantitative measurements of the detachment force of *Hydra* has been performed.

Measuring the force for detachment of larger animals, such as *Mytilus* sp. has involved mechanical spring-based instruments (Bell and Gosline, 1996; Denny, 1987), while sea anemone detachment has been measured using force transducers (Koehl, 1977). Such instruments, however do not mimic the naturally occurring flows that aquatic animals are likely to experience and measurements could suffer from artefacts arising from contact. Flow chambers address some of these shortcomings and have been

used to study biofouling using turbulent (Schultz et al., 2000) or pumped flows coupled to inline flow meters (Neal et al., 1996). Flow tanks that have been described for whole organism studies (Vogel and LaBarbera, 1978) and parallel-plate flow chambers used for studying leukocyte adhesion (Chen and Springer, 1999) are successful means to measure detachment dynamics of samples, ranging from cells to whole organisms.

We have chosen to characterise the biomechanics of *Hydra* sp. detachment with calibrated fluid flows, from which we estimate the drag force required to displace the animal from a substrate. We use this device to measure the flow rate required to detach the *Hydra* from substrates of different stiffness and proceed to examine the role that starvation and substrate stiffness play in the stress required to detach the individuals.

Materials and Methods

Growth and handling of *Hydra*

Hydra vulgaris Ind-Pune (Reddy et al., 2011) and *Hydra magnipapillata* were obtained from ARI (Pune, India). They were maintained in ~200 ml of "M" solution containing 0.1 mM KCl, 1 mM NaCl, 1 mM $\text{CaCl}_2 \cdot 2\text{H}_2\text{O}$, 1 mM Tris (pH 8) and 0.1 mM $\text{MgSO}_4 \cdot 7\text{H}_2\text{O}$ in water (Sugiyama and Fujisawa, 1977). The animals were maintained at 18°C in an incubator with a lamp, with timer kept on for ~12 h to artificially induce day-night cycles (Thermo Scientific, USA) and the beaker cleaned on a daily basis. *Hydra* were fed two to three hatched *Artemia* sp. (brine shrimp) every two days. Brine shrimps were grown in a 0.6% saline solution and filtered after washing in tap water before being used as feed.

Imaging and Microscopy

Individual *H. vulgaris* and *H. magnipapillata* animals were placed in a petri dish with a drop of 'M' solution to prevent desiccation and imaged using a Leica dissection microscope S8 APO illuminated with a Leica (24 DC) LED control unit and equipped with an EC 3 camera (Leica Microsystems, Germany). The onset of turbulence was recorded using autofocus and automatic exposure settings in video mode on a Canon EOS 1000D camera (Canon Inc., Japan).

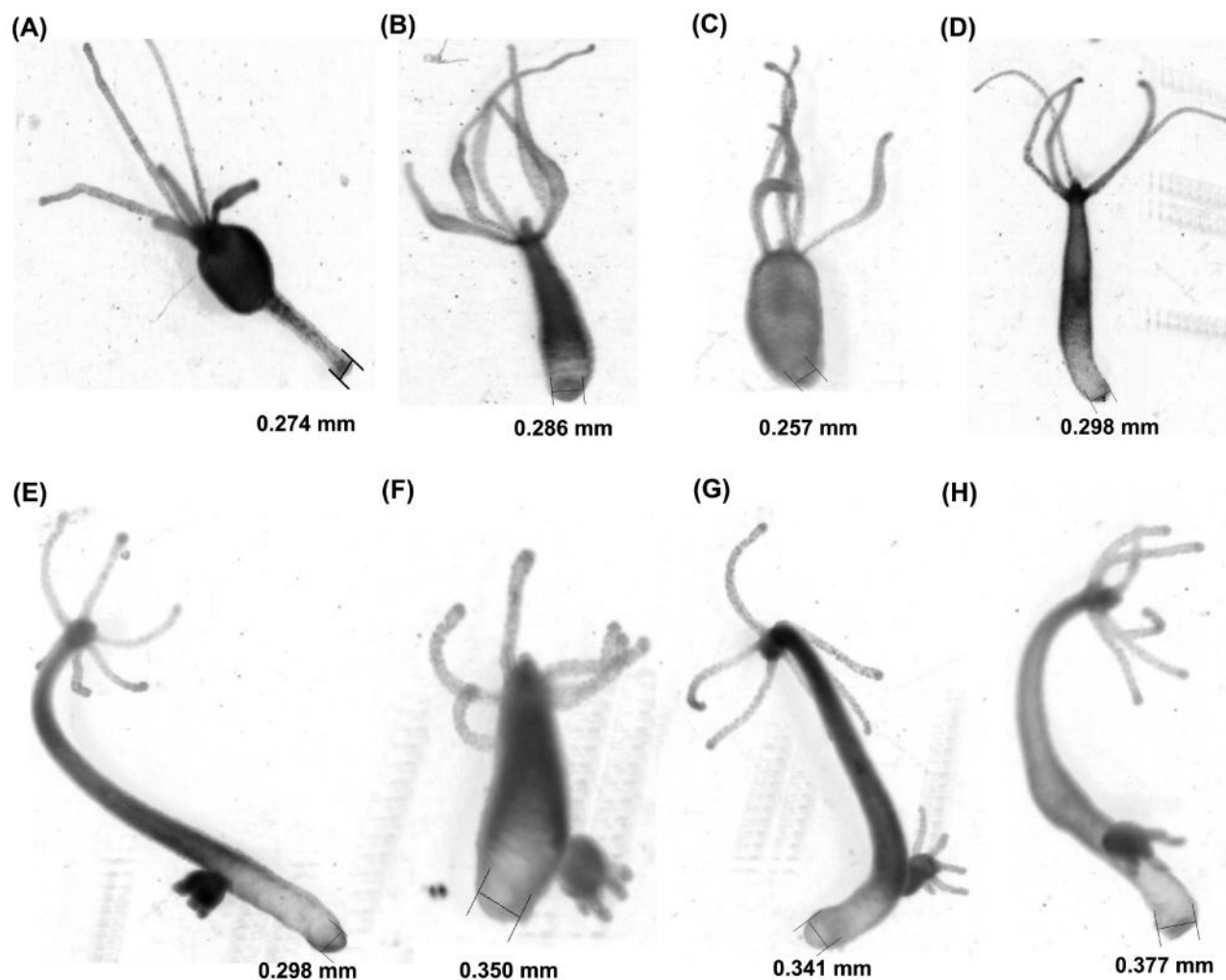


Fig. 1: Estimating the size of *Hydra*. Images of live animals of (A)–(D) *Hydra vulgaris* and (E)–(H) *Hydra magnipapillata* were acquired under a dissection microscope in a drop of “M” solution. The base diameter is marked at the measured site in millimeters (mm). Mean diameters *H. vulgaris* 0.279 mm and *H. magnipapillata* 0.342 mm

Flow Chamber and Detaching Hydra

A syringe pump (PhD Ultra, Harvard Apparatus, USA) with a 20 ml plastic syringe (BD Biosciences, India) was connected to polycarbonate tubing of inner diameter (I.D.) 3 mm (BioRad, USA) and further connected with an adaptor (BioRad, USA) to a tube of I.D. 0.8 mm, taped to the bottom of a glass trough (Fig. 2A). For *Hydra* detachment experiments, the animals were allowed to attach to a glass coverslip (MicroAid, Pune, India), such that the animal was at a distance of 0.5 cm from the tube outlet, in line with the fluid flow. Flow experiments typically involved increasing the flow rate from 10 ml/min, with increments of ~ 2 ml/min until the animal detached due to the force generated. Those experiments in

which the *Hydra* was either attached to the substrate with its tentacles, or did not attach at all, or failed to detach at all flow rates were ignored in analysis of detachment shear stress. The sample sizes for each animal and condition ranged from 7–10 animals (Table 1).

Table 1: The sample sizes of *Hydra* sp. detachment under different conditions

Organism	Substrate	Feeding status	No. of individuals
<i>Hydra vulgaris</i>	Glass	Fed	10
		Unfed	10
	Gel	Fed	7
		Unfed	10
<i>Hydra magnipapillata</i>	Glass	Fed	10
		Unfed	7

Modulating Substrate Stiffness

For experiments to measure the effect of substrate stiffness, a 0.75 mm thick 5% polyacrylamide gel was prepared using a 5 ml solution of 5% acrylamide and 0.22% bisacrylamide, 25 ul APS (1/200 volume) and 2.5 TEMED (1/2000 volume) (all reagents Sigma-Aldrich, Mumbai, India) and curing for 15 min between two plates was layered with water in a standard polyacrylamide gel electrophoresis (PAGE) setup (BioRad, USA). This gel of stiffness of 8 kPa (Tse and Engler, 2010), was layered on the coverslip and the *Hydra* was allowed to attach to the gel. The remainder of the experiment was performed in a manner similar to the experiments for detaching *Hydra* from glass coverslips.

Data Analysis

Images of *Hydra* and the onset of turbulence were processed using Image J (Schneider et al., 2012). Fitting data to functions was performed using the non-linear fitting tool (*nlinfit*) in MATLAB (Mathworks Inc., MA, USA). Statistical testing of mean shear stresses was performed using a two-sided Kolmogorov-Smirnov (KS) test with 95% confidence interval.

Results

Morphometry of *Hydra* and Profile in Flow

In order to estimate the forces exerted by flow, we needed to characterise the shape and size of *Hydra* used in this study. Two species were chosen due to the differences in sizes and availability, namely *H. vulgaris* and *H. magnipapillata*. While qualitatively in a dissection microscope *H. vulgaris* was seen to be shorter than *H. magnipapillata*, their widths appeared comparable (Fig. 1). This was confirmed by estimating the mean cross-sectional diameter of the foot as 0.279 mm for *Hydra vulgaris* (Fig. 1A-D) and 0.342 mm for *H. magnipapillata* and height as 3 and 5 mm respectively (Fig. 1E-H). Given the base of the hydra is approximately circular, we calculate the average disk area (A_d) of *H. vulgaris* to be 0.24 mm² and *H. magnipapillata* to be 0.37 mm².

Laminar Flow in Chamber and Positioning *Hydra*

The flow chamber set-up consists of a syringe pump

connected by tubing to a trough filled with medium. The *Hydra* are submerged in the medium and subjected to the flow (Fig. 2A). We proceeded to characterise the nature of fluid flow in the chamber, in order to test whether the forces generated are due to laminar flows.

To this end, the experiment was performed in absence of any obstacles to characterise the syringe pump driven water jet. Safranin dye was added to the water in the syringe in order to provide contrast for visualizing the flow as it entered the trough. We observed turbulence in the flow at a distance L_t from E, the exit from the pipe (Fig. 2B). The point of turbulence, along the length of the flow was marked as T. The graph of L_t as a function of flow rate (Q) shows that even for the fastest flow-rates, the eddies begin 1 cm from the pipe exit, E (Fig. 2C).

In order to understand the quantitative nature of the flow rate dependence of the length of turbulence onset, we attempted to empirically model this data based on the theory of turbulence due to a moving fluid entering a static body of the same fluid. We fit the data of L_t with changing Q by modifying the standard expression for Reynolds number (Re). By definition, $Re = (\rho \cdot L \cdot V)/\eta$, where, ρ ($kg \cdot m^{-3}$) is the density of fluid, $L(m)$ is the characteristic length of the flow, V ($m \cdot s^{-1}$) is the fluid velocity and η ($N \cdot s \cdot m^{-2}$) is the dynamic viscosity. By dimensional analysis, the volume flow rate Q with units $m^3 \cdot s^{-1}$, is related to the fluid velocity by:

$$V = Q/A_f \quad (1)$$

where, A_f (m^2) is the area of cross section of the fluid flow. Substituting for V and based on the fact that Re , ρ , η and A are constant for a given flow rate, we invoke a lumped constant $c_1 = (Re \cdot A \cdot \eta)/\rho$. The characteristic length at the point of turbulence is the length of turbulence onset, L_t . As a result, we arrive at the following expression:

$$L_t = c_1/Q \quad (2)$$

which we proceed to fit to the experimental data in Fig. 2C. The fit value of c_1 is 1.06 cm^4/s . Based on this fit, L_t is always greater than 1 cm for all values of the flow rate Q that were used in experiment.

For comparison, we used results from environmental fluid mechanics, where the distance

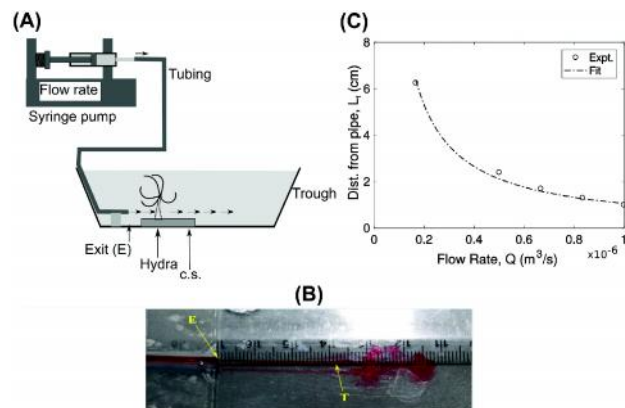


Fig. 2: Detachment of Hydra in a laminar flow device. (A) A schematic representation of the experimental set-up with *Hydra* placed on a coverslip (c.s.) at a fixed distance from the pipe exit (E) submerged in buffer in a glass trough. The arrows indicate direction of flow of water from the syringe pump. (B) The view from the top of distance of the onset of turbulence (T) flow from the pipe exit (E) estimated by flowing safranin containing water. (C) The turbulence length (L_t) is plotted as a function of the flow rate, Q (circle) and fit (dashed line) by the equation $L_t = c_1/Q$ (Equation 2)

before the onset of spreading of the flow in an analogous system to ours, is also referred to as the ‘virtual source’ distance from the exit nozzle and is $5r$, where, r is the radius of the pipe (Cushman-Roisin, 2006). The tubing used for the flow device has an inner diameter of 0.3 cm, resulting in a virtual source distance of 0.75 cm from the nozzle. Based on these results, we placed *Hydra* at a distance of 0.5 cm from E in subsequent experiments, to ensure that the force experienced is due to laminar flows alone.

Relating Drag Force Experienced by Hydra to the Flow Rate

Since *Hydra* is an aquatic animal, we used the flow of water to generate force to detach it, since it avoids potential artefacts of mechanical attachment of the organism to a cantilever. The fluid drag force experienced by sessile animals in a moving fluid has been previously described by Vogel (Vogel, 1996), through the standard drag equation based on Bernoulli’s principle. For sessile animals in a flow, it has been shown to depend on the frontal projecting area of the animal with simplifications of the animals to standard geometric forms. We have therefore

assumed a simplified geometry for *Hydra* - a cylinder. Further, the section of the cylinder experiencing the flow (half the area of the cylindrical section) then becomes the projected area (A_p) as seen in in Fig. 3A. Then, drag-force (F_{drag}) experienced by the *Hydra* can be estimated by:

$$F_{drag} = C_d \cdot \rho \cdot V^2 \cdot A_p / 2 \quad (3)$$

where, C_d is the drag coefficient, ρ is the density of the fluid, V is the velocity of flow and A_p is the projected area of the body in the path of fluid flow, shown schematically in Fig. 3A. On substituting V from Equation 1 into the expression for drag force (Equation 3), we obtain an expression of the drag force, in terms of volume flow rate:

$$F_{drag} = \frac{C_d \cdot \rho \cdot Q^2 \cdot A_p}{2 \cdot A_j^2} \quad (4)$$

Thus, the detachment force of *Hydra* can be calculated using Equation 4, based on two assumptions that justify the use of the V (and in turn Q) values of the jet of water as it exits the pipe:

1. The *Hydra* are placed at a distance from the pipe that is always less than the distance, where turbulence onset is observed (Fig. 2).
2. Dissipation of the flow due to spreading can be ignored, since the *Hydra* are placed at a distance less than the ‘virtual source’ distance.

The drag coefficient (C_d) is a dimensionless constant and depends on properties of the object and fluid such as shape and Reynolds number. For our calculations, choice of C_d was made by approximating the shape of *Hydra* to a cylinder with its long axis normal to the direction of flow. Based on the length:width ratio of *Hydra*, the drag coefficient of 0.68 was chosen, based on standard results for a cylinder with length to the diameter ratio of 2:1 (Stoecker, 2004). For the sake of simplicity, we assumed the shape to be constant for the *Hydra* across all the conditions.

The calculated estimates of force with increasing flow rate was calculated, based on a function of the form:

$$F_d = c_2 \cdot Q^2 \quad (5)$$

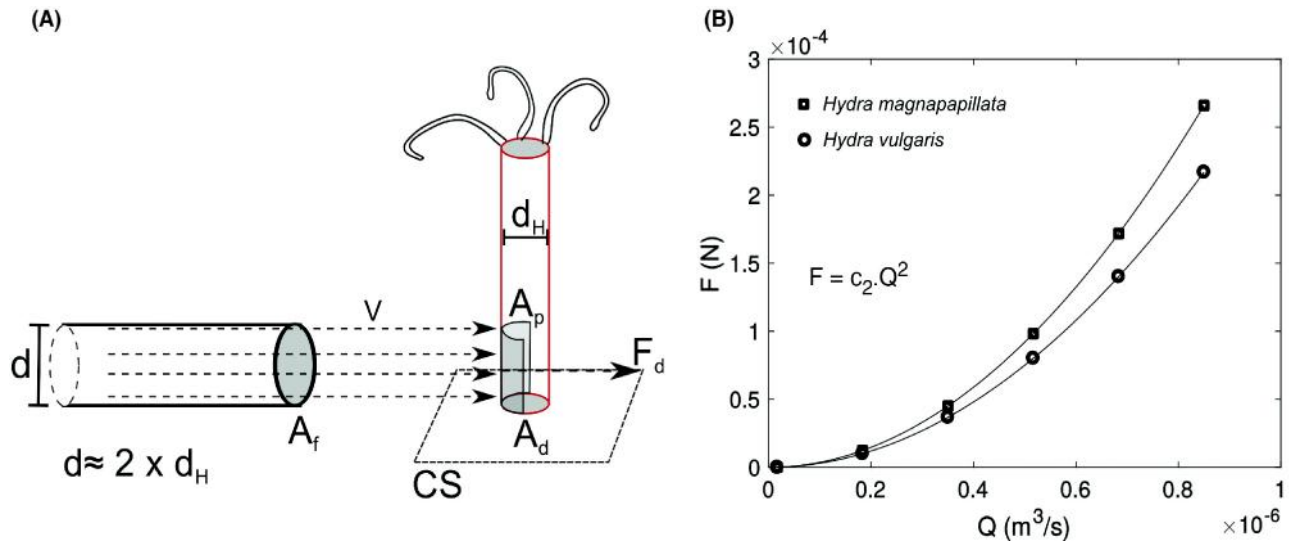


Fig. 3: Forces acting on *Hydra*. (A) The schematic represents the direction of fluid flow from the exit of the tube with the *Hydra* experiencing a drag force (F_d) along the direction of flow velocity (v). For simplicity, the animals are assumed to be in an upright orientation with a simplified cylindrical geometry. A_f : flow cross-sectional area; A_p : projected area of the *Hydra* in flow, A_d : A_d disk area of *Hydra*, d : inner diameter of pipe and CS: coverslip. From measurements $A_f \approx 2 A_d$. (B) The drag force experienced by *Hydra* due to flow is calculated from Equation 5 with the constant c_2 calculated for *Hydra vulgaris* to be $3 \times 10^8 \text{ kg m}^{-5}$ (circles) and for *Hydra magnipapillata* to be $3.68 \times 10^5 \text{ kg m}^{-5}$ (square)

where, Q is the volume flow rate (cm^3/s) and $c_2 = (C_d \cdot \rho \cdot A_p)/2 \cdot A_p^2$ is a constant that differs for the two species due to the differences in the projected area A_p . The values of c_2 , obtained by substitution, are $3 \times 10^8 \text{ kg.m}^{-5}$ for *Hydra vulgaris* and $3.68 \times 10^8 \text{ kg.m}^{-5}$ for *Hydra magnipapillata*. Based on Equation 5, we can plot the force for both species across the range of flow rates used experimentally (Fig. 3B). By noting the flow rate at which mechanical detachment of *Hydra* is observed, we can then estimate the shear force of detachment.

Estimating Detachment Force Variation with Species, Feeding State and Substrate Rigidity

In order to measure detachment forces, as a first step, individual *Hydra* were allowed to attach to a glass coverslip (coated or uncoated) in the incubator. At the time of measurement, the coverslip was removed from the incubator and placed at a distance of 0.5 cm from the pipe exit (E) (Fig. 2A). The flow rate (Q) was gradually increased until the *Hydra* detached. Measurements were repeated for 10 individuals of *H. vulgaris* and *H. magnipapillata*. By starving one set of animals, we addressed the effect of nutritional state. We also compared the effect of changing substrate stiffness on *H. vulgaris*. For

each experimental condition, the flow rate at which *Hydra* detached was used to calculate the force of detachment (Equation 5). It is reasonable to assume that both species have a circular cross-section. Hence, the area of the basal disk is estimated from the mean diameter of each species. The ratio of the detachment force to the basal disk area then results in shear stress of detachment. *H. vulgaris* detaches from glass substrates over a wide range of shear stresses, ranging from 0.57 to 2.02 MPa, while *H. magnipapillata* detachment shear stresses range between 3 and 3.7 MPa (Fig. 4A). While the difference between detachment shear stress of fed and unfed *H. vulgaris* is not statistically significant, that between substrates of glass and 5% polyacrylamide gel is significant, for the same species in the same nutritional state. However, the shear stress required to detach *H. magnipapillata* is higher than that for *H. vulgaris* in the same nutritional state, while the animals are attached to glass. All comparisons were based on a two-sided Kolmogorov-Smirnov test, with 95% confidence interval. Based on our measurements, the detachment shear stress is estimated to be of the order of 10^2 – 10^3 N/m^2 , which is two orders of magnitude, smaller than in molluscs (Denny, 1987). This suggests that the *Hydra* adhere

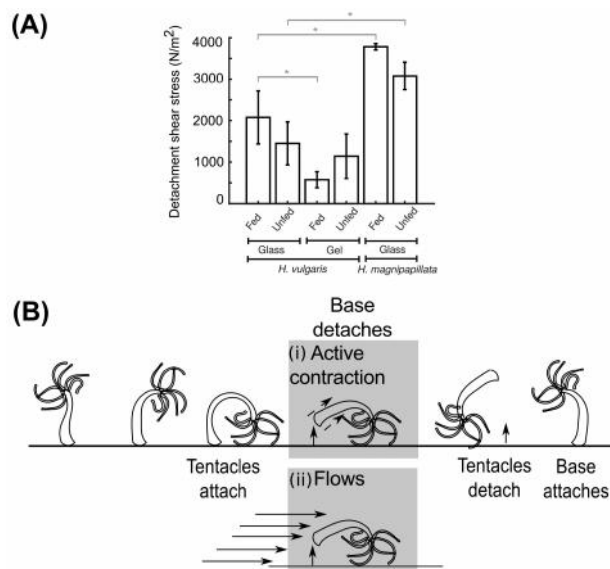


Fig. 4: Detachment shear stress. (A) The mean shear stress (\pm s.e.m.) of detachment for *H. vulgaris* and *H. magnipapillata* under fed and unfed conditions for individual hydra attached to glass (stiffness 7.29×10^7 kPa). *H. vulgaris* detachment was also tested on a 5% polyacrylamide gel (stiffness ~ 8 kPa). The mean shear stress was compared, using a two-sided Kolmogorov-Smirnov test at $\alpha = 0.05$ (*). (B) The schematic depicts the stages in ‘somersaulting’ movement by *Hydra*. The stage of detachment of base from the substrate can be driven either by (i) active contraction along the body-length or (ii) the force generated by flows in the environment

to their substrate, with a weak glue in a manner that depends on the substrate-stiffness and the species.

Discussion

Here, for the first time we have quantitatively characterised the mechanics of *Hydra* detachment from an attached position on a substrate. We use a simple flow device which generates known amounts of shear stress through flows generated in the aqueous. We can show that smaller shear stresses are required to detach *H. vulgaris* from soft as compared to hard substrates. We find that the shear stress of detachment between fed and unfed states shows no statistically significant difference for the same substrate of both *H. vulgaris* and *H. magnipapillata*.

The steady attachment of sedentary aquatic animals can occur by multiple mechanisms, but the strength of attachment to the substratum is related to

its behaviour, as well as the flows in which it lives (Koehl, 1977; Dodou *et al.*, 2011; Ditsche and Summers, 2014). Typically, free flowing streams with a gentle flow are reported to have flow speeds in the range of 0.5 m/s to 3 m/s. We can make an order of magnitude estimate of the shear stress (S) based on the fluid drag-force (F_{drag}) from Equation 3 which simplifies to $S = \rho \cdot v^2/2 \cdot r$ using the C_d of 0.68 based on the 2:1 ratio of length to the diameter (Stoecker, 2014) of *Hydra* and assuming the *Hydra* can be treated as cylinders, so the projected half-area of the cylinder is affected by drag. Based on an estimate of the projected areas of the two species, *H. vulgaris* will be expected to experience shear stresses between 1.8×10^3 and 6.6×10^4 N/m², while *H. magnipapillata* is expected to experience between 2.5×10^3 and 8.9×10^4 N/m². Given that we measure detachment shear stresses for both species, ranging between 5×10^2 and 3.7×10^3 N/m² (Fig. 4A), it would suggest normal flows that the animal is likely to experience, would be sufficient to detach the animal from the substrate. This would suggest, that in addition to active motion, *Hydra* can also be passively detached from its substrate. This is corroborated by observations of drifting animals found in their natural habitat. Careful observations in still and moving streams combined with measurements of flow-rates *in situ* could be potentially used to test this prediction.

The measurements we report here are made on two kinds of artificial substrates—glass and 5% polyacrylamide gel. While glass is very stiff with a Young’s modulus of 72.9 MPa, the gel used has a reported stiffness of 8 kPa (Tse and Engler, 2010). Our measurements suggest that *Hydra vulgaris* is less firmly attached on a soft substrate, as opposed to a hard substrate. The comparison with the bulk modulus of elasticity of freshwater aquatic plant leaves, which ranges between 1 and 10 MPa (Touchette *et al.*, 2014), would suggest our measurements cover the range of stiffness that *Hydra* could be expected to encounter when attached to leaves. While on the one hand, the differences in detachment are less than an order of magnitude and subject to large variations, it would be interesting in future to systematically vary substrate stiffness and examine the role it plays in movement of the animal. Additionally, the mechanical properties of specific plants and other objects to which *Hydra* is naturally found attached to, could also determine whether there

is any role at all for the substrate stiffness.

In our experiments, we have used inert substrates during the detachment measurements, in order to study the role of mechanical properties in the absence of any material properties. However, it could have been possible that the chemical nature of the 'glue' might also be modulated during detachment, through hydrolysis by some enzyme produced in the animal itself. However, a recent study that investigated the glue concluded that active contraction is more likely to be the primary method by which *Hydra* achieves detachment (Rodrigues *et al.*, 2016a). Since we do not observe a clear starvation dependent weakening of the bond, our data corroborates the potential role of active contraction. A potential limitation of the current study is that we only observed whether the animal has detached from its base (end-point), since we do not record the motion prior to its detachment. However, even if it were to perform 'somersaulting' locomotion during the measurement, the fact that, the flow diameter is approximately 1/10 the length of the *Hydra* (Fig. 3A) suggests the validity of our approach. In future, the predictions of either 'somersaulting' or passive detachment of *Hydra* could be tested by motion-capture videography to capture the entire cycle of movement (Fig. 4B).

The force required to detach *Hydra* is two orders of magnitude smaller than the detachment stress of reported for the well studied sedentary marine mussel *Mytilus* sp. (Denny, 1987). We hypothesise that the difference in habitat of *Hydra* sp. which mostly inhabits ponds and slow-flowing streams means that the detachment stresses do not need to be as high as those observed in *Mytilus* mussels, typically found attached to inter-tidal rocks subject to constant wave action (Bell and Gosline, 1996). Based on reports by Annandale and others, it is reasonable to assume this weaker adhesion of *Hydra* is an adaptation to the forces generated by currents it usually experiences in its natural habitat and for the mode of motility that it adopts.

The measurement setup, while simple, provides useful initial answers to a mechanical approach to animal behaviour. Potentially, in future, higher flow rate methods would require taking into consideration the turbulent regime (Schultz *et al.*, 2000). In addition, the starvation conditions in the native environment

that trigger 'somersaulting' movement are not clearly reported. In our work, we have empirically chosen a week of starvation. In future a controlled study on the factors and duration of nutrient withdrawal, combined with mechanics could help us better understand the triggers that govern the decision of *Hydra* to move.

In conclusion, we have characterised the shear stress of detachment of two species of *Hydra* and find them to range between 0.5 and 3.7 kPa. The detachment stress is independent of the nutritional state (i.e. fed as compared to starved for one week) and shows a small change with substrate-stiffness. In addition, we find that *H. magnipapillata* is detached at a higher stress value, as compared to *H. vulgaris*. Based on its natural environment, where the animal is typically found attached to the under side of leaves in ponds and lakes, it would appear that ambient flows by themselves could generate comparable shear stresses of detachment. During 'somersaulting' locomotion, the forces required to be generated by the muscles will also necessarily need to be of comparable magnitude as the detachment stress reported here. This sets the stage for a more quantitative understanding of both passive and active modes of locomotion of *Hydra* in its natural habitat.

Author contributions

NK performed the calculation, made the figures and wrote the manuscript SM assembled the device, performed the measurements and acquired the images CAA conceptualized the study, made the figures, wrote the manuscript and supervised the study.

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Competing interests

The authors declare they have no competing interests.

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